

Fast emission estimates in China and South Africa constrained by satellite observations

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PRESCRIBE workshop, 16 May 2013

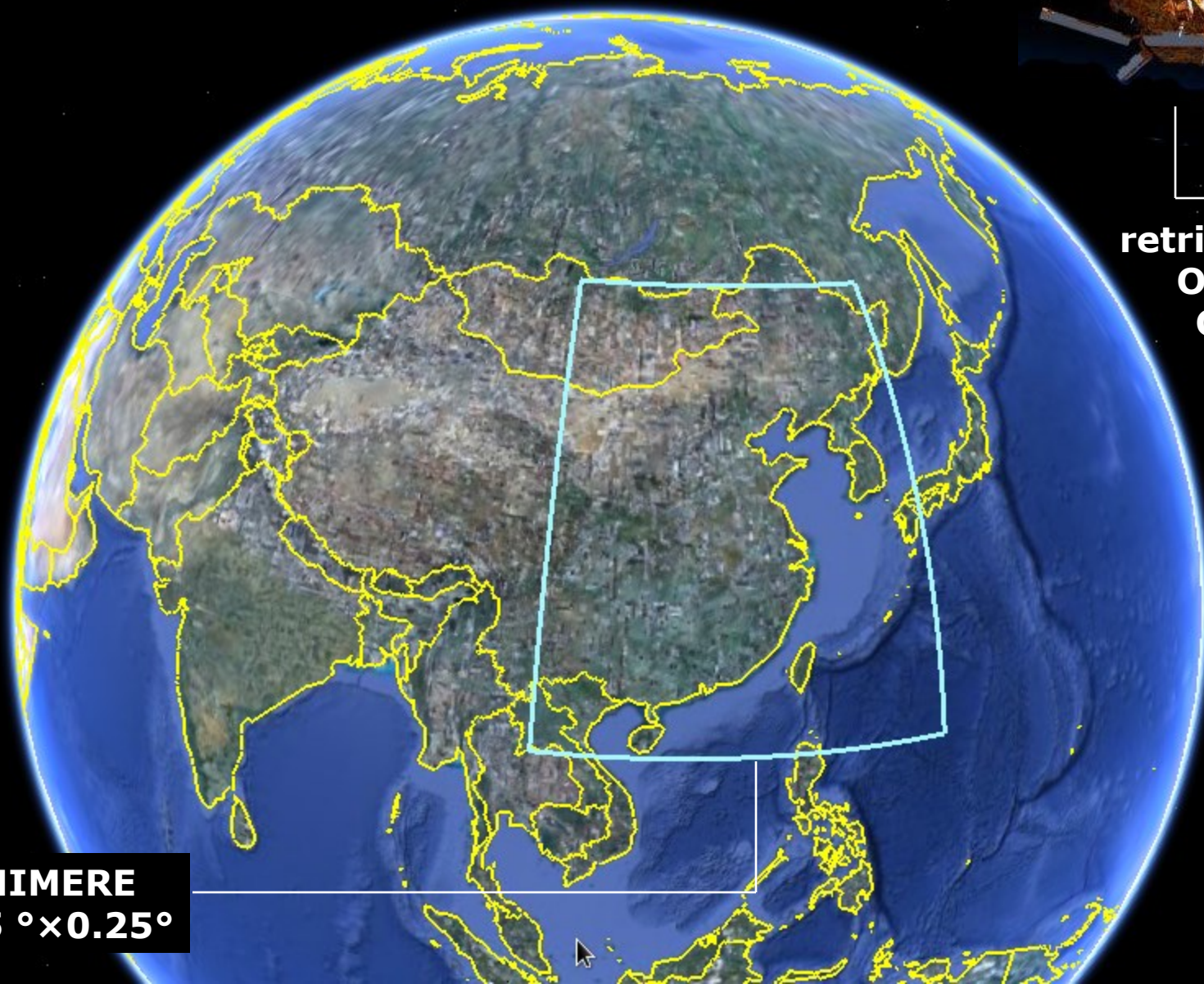
Overview

- New emission estimation algorithm
- Applied to China
 - NO_x emission trend analysis 2007-2011
- Applied to South Africa
 - First results of NO_x emissions

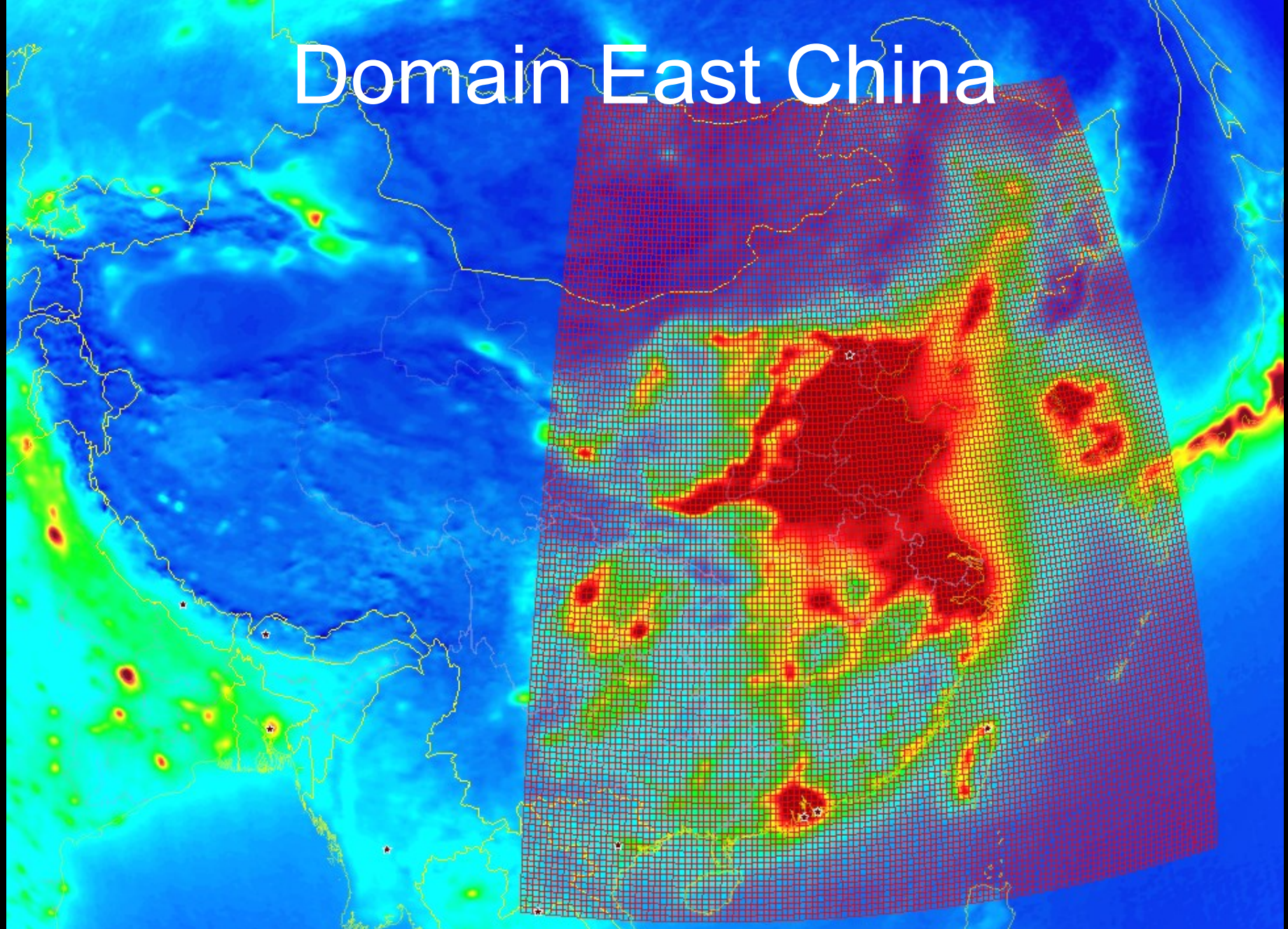
Basic tools

CHIMERE
0.25 °×0.25°

NO₂
retrievals from
OMI and
GOME2



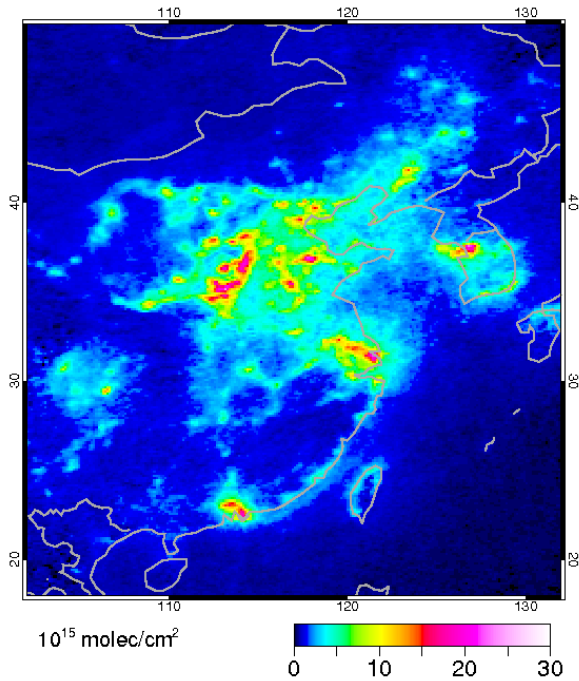
Domain East China



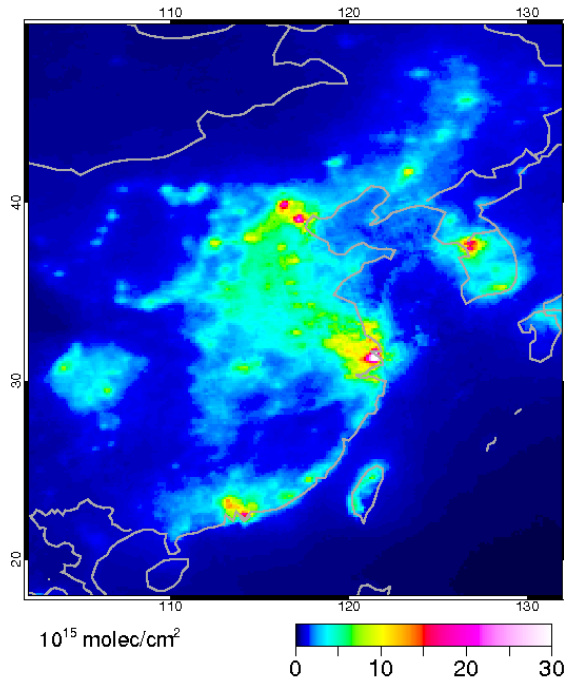
18°N–50°N, 102°E–132°E, 0.25° resolution, 15609 grid cells

Difference between observations and model

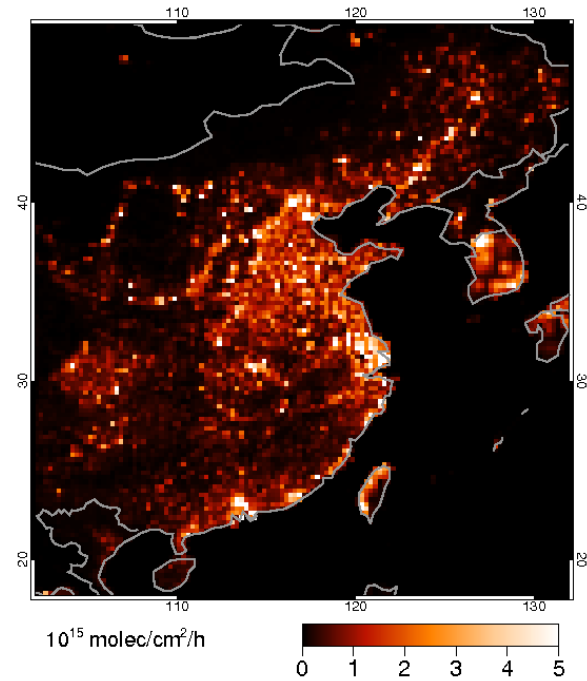
OMI tropospheric NO₂



CHIMERE tropospheric NO₂



INTEX-B 2006



Average over June–August 2008

Inversion techniques

finding the relation between emission changes and concentration changes

- **Adjoint code of CTM**
Not always available.
- **Ensemble Kalman Filter**
Multiple forward model runs necessary.
- **Local inversion by concentration ratio**
e.g. by Martin et al. (2006). Transport from source neglected.
- **DECSO** algorithm *(Mijling and Van der A, JGR, 2012)*
Daily **E**mission estimates **C**onstrained by **S**atellite **O**bservations

Only 1 model run necessary:

Algorithm is relatively fast, enabling daily inversion of observations.

Transport from source is included:

Enabling emission estimation on a mesoscale resolution (10-25 km)

Using a simplified 2D transport scheme to approximate CTM run

Two concentration contributions

Consider a time interval $t=[0,T]$ (24 hrs).

The concentration at $t=T$ is composed of

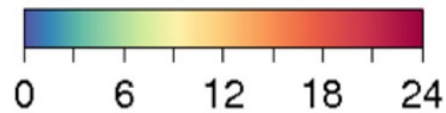
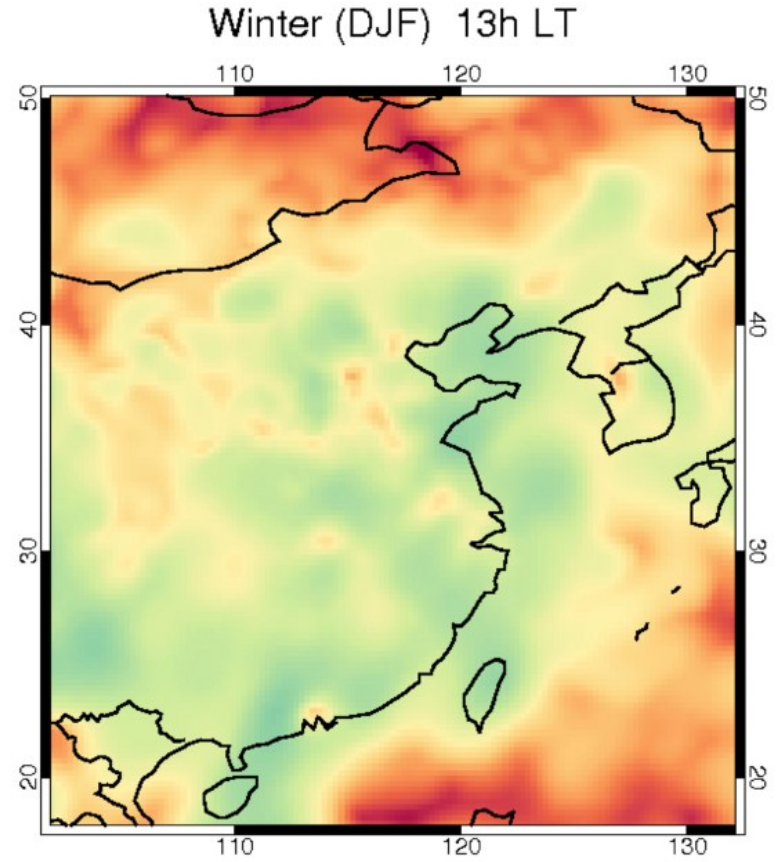
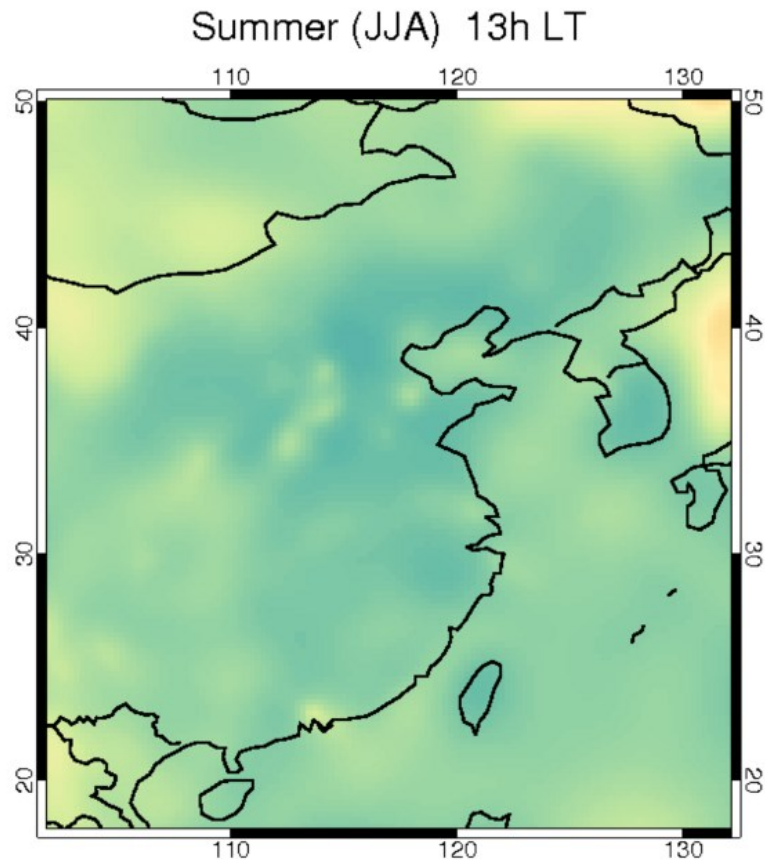
1. Transported and aged background concentration:

$$c_i(T) = \sum_j \exp(-T/\tau_j) \Omega_{j \rightarrow i}(T) c_j(0) \Rightarrow \mathbf{c}(T) = \mathbf{Gc}(0)$$

2. Emitted and transported NO_x during the time interval:

$$c_i(T) = \sum_j \left(\int_0^T \exp(-t/\tau_j) \Omega_{j \rightarrow i}(t) f_j(T-t) dt \right) e_j \Rightarrow \mathbf{c}(T) = \mathbf{He}$$

Effective lifetime



Dependence of NO_2 columns in grid cell i on NO_x emission changes in grid cell j

$$H_{ij} = \frac{\partial c_i^{\text{NO}_2}}{\partial e_j^{\text{NO}_x}} = \gamma_i \frac{a_j}{a_i} \int_0^T e^{-t/\tau_j} \Omega_{ij}(t) f_j(T-t) dt$$

$[0, T]$ 24h time window between two satellite overpasses

$f_j(t)$ diurnal emission modulation

$\Omega_{ij}(t)$ transport of NO_x from cell j to i during $[t, T]$

τ_j effective lifetime of NO_x

a_j/a_i ratio grid cell area

γ_i NO_2/NO_x ratio

The sensitivities \mathbf{H} are interpolated to the satellite footprints and are corrected for by the averaging kernel of the retrieval method.

Inversion problem

$$\Delta c = H \Delta e$$

The diagram illustrates the inversion problem as a matrix equation. On the left is a vertical green rectangle labeled Δc . In the center is a large green rectangle labeled H containing the partial derivative expression $\frac{\partial c_i}{\partial e_j}$. On the right is another vertical green rectangle labeled Δe . An equals sign is placed between the left and center rectangles. A red oval with the text "underdetermined problem!" is positioned below the H matrix.

Difference satellite
observation and
model simulation
over East China

Sensitivity matrix
 $\sim 2000 \times 15000$

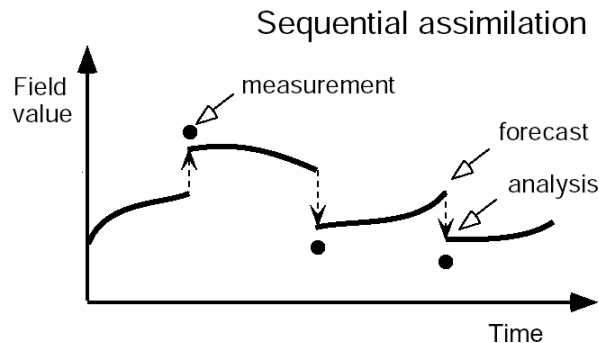
Update emission
inventory (0.25°)
over East China

Inversion: The Kalman Filter

State vector forecast	$\mathbf{x}^f(t_{i+1}) = M_i [\mathbf{x}^a(t_i)]$
Error covariance forecast	$\mathbf{P}^f(t_{i+1}) = M_i \mathbf{P}^a(t_i) M_i^T + \mathbf{Q}(t_i)$
Kalman gain matrix	$\mathbf{K}_i = \mathbf{P}^f(t_i) \mathbf{H}_i^T [\mathbf{H}_i \mathbf{P}^f(t_i) \mathbf{H}_i^T + \mathbf{R}_i]^{-1}$
State vector analysis	$\mathbf{x}^a(t_i) = \mathbf{x}^f(t_i) + \mathbf{K}_i (\mathbf{y}_i^o - H_i [\mathbf{x}^f(t_i)])$
Error covariance analysis	$\mathbf{P}^a(t_i) = (\mathbf{I} - \mathbf{K}_i \mathbf{H}_i) \mathbf{P}^f(t_i)$

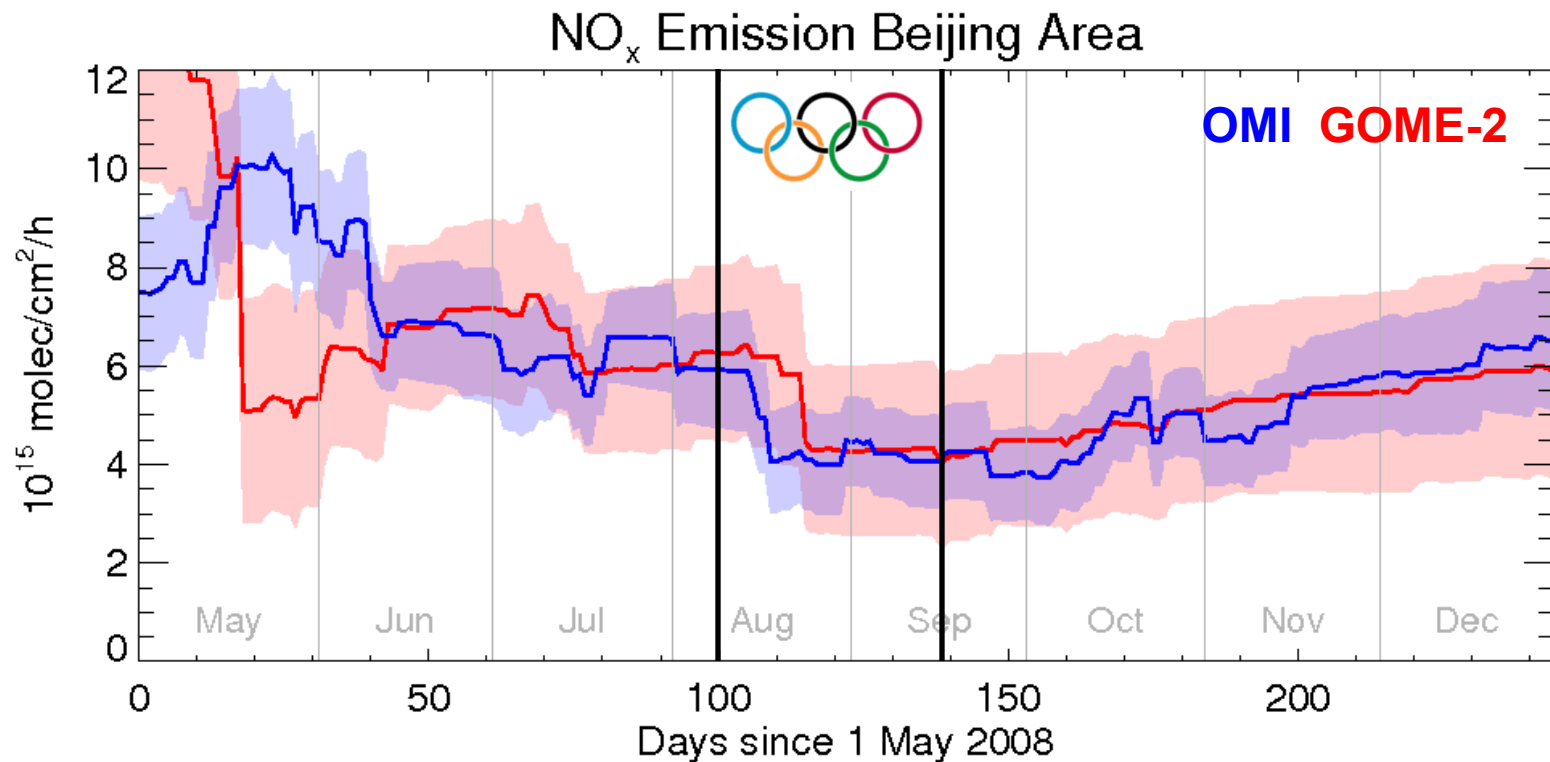
- Starts from *a priori* information, i.e. the best known bottom-up emission inventory

- Update depends on error in observation and simulation

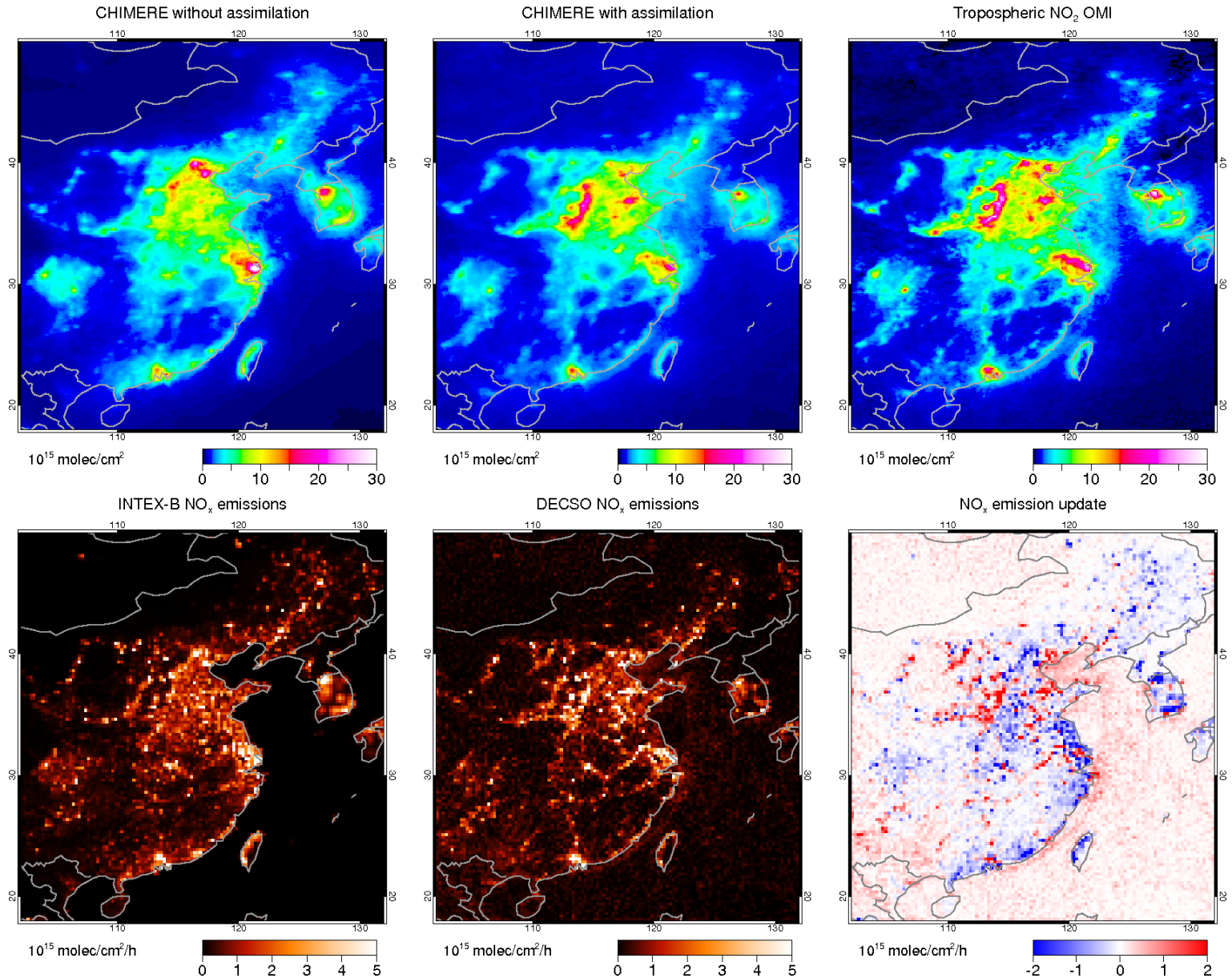


- No update where no information is available
- Emissions are updated by addition instead of scaling
- Error estimation of new emission inventory

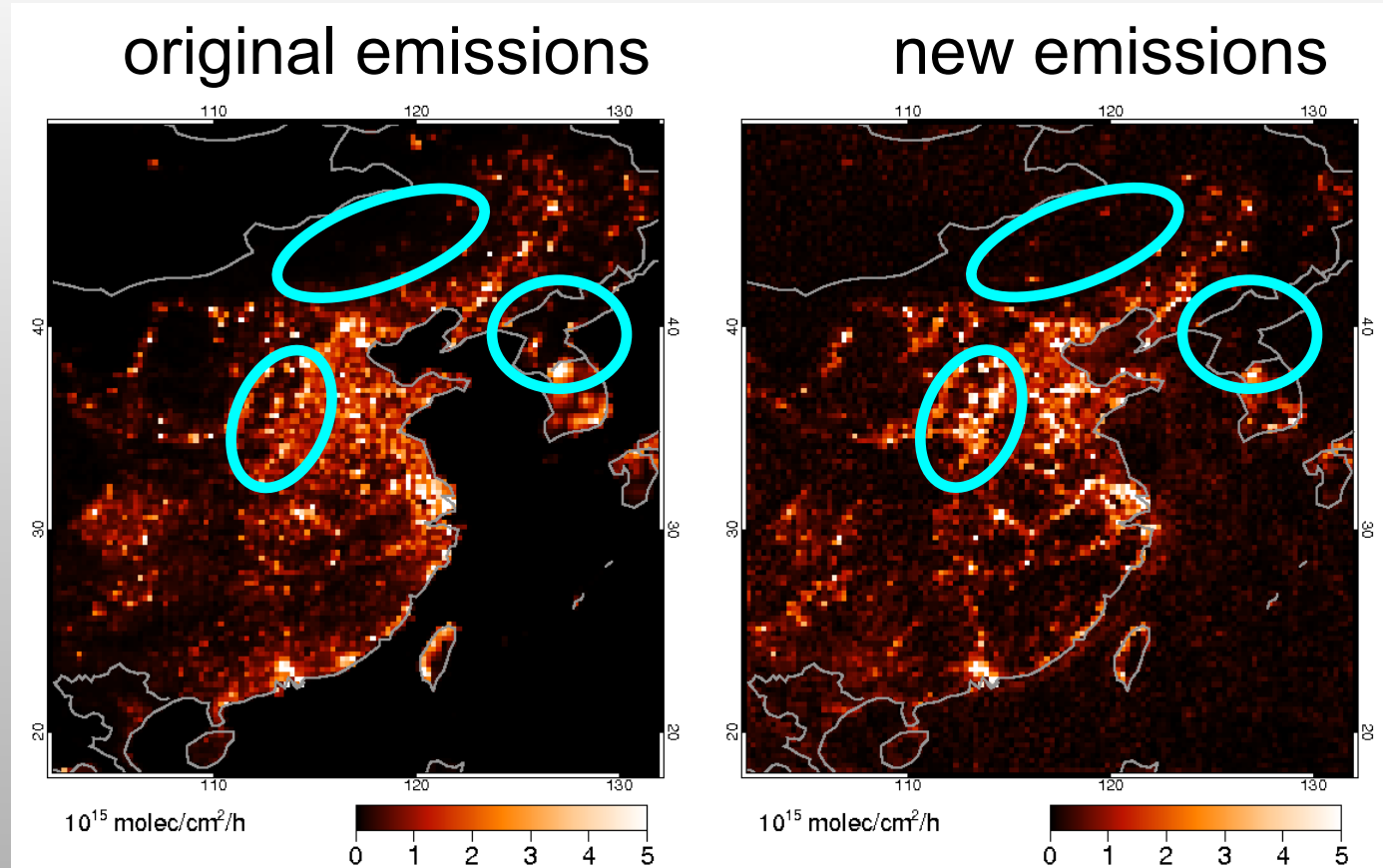
NO_x emission trend Beijing area



NO_x emission estimates for East China

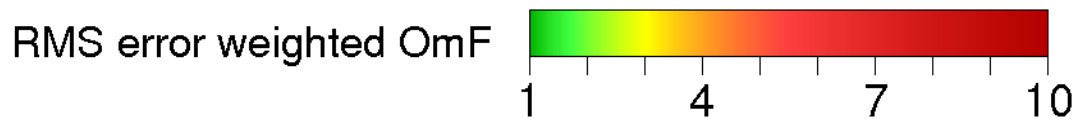
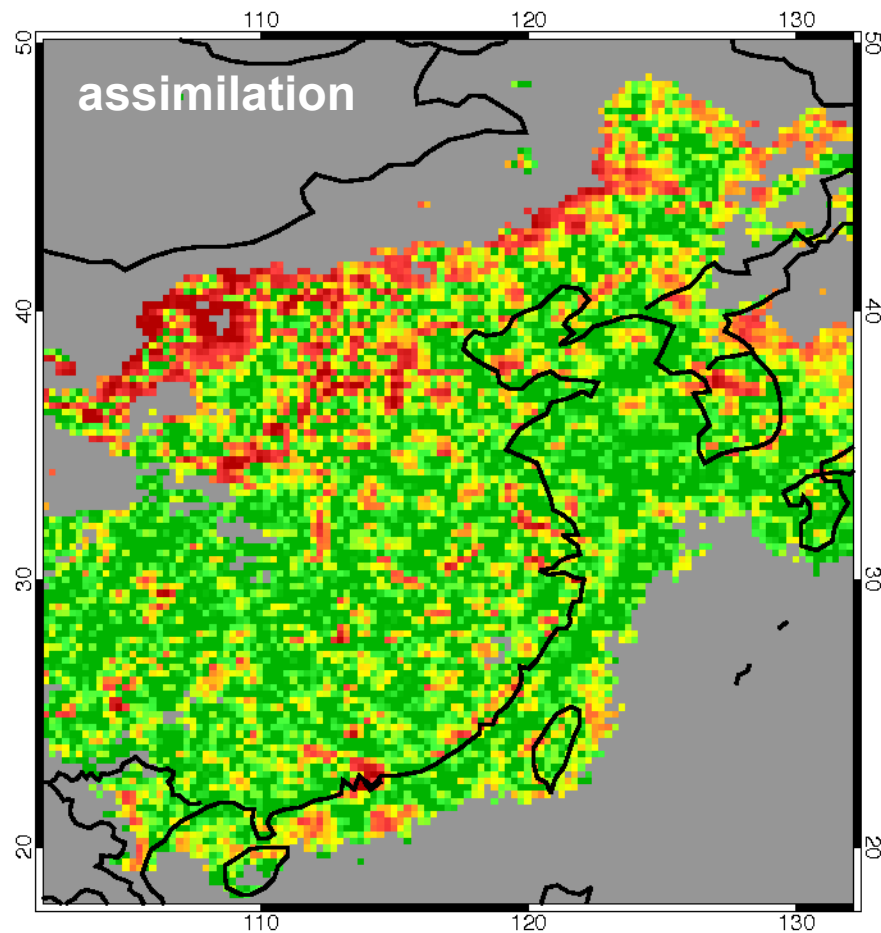
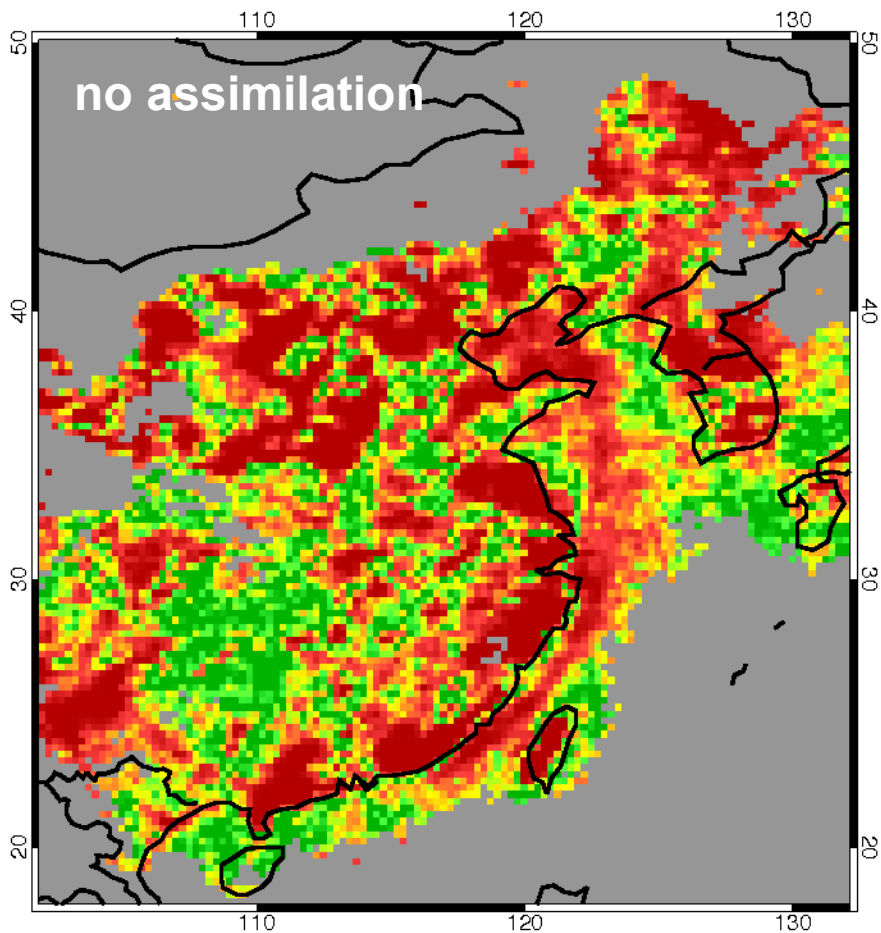


Emission results China



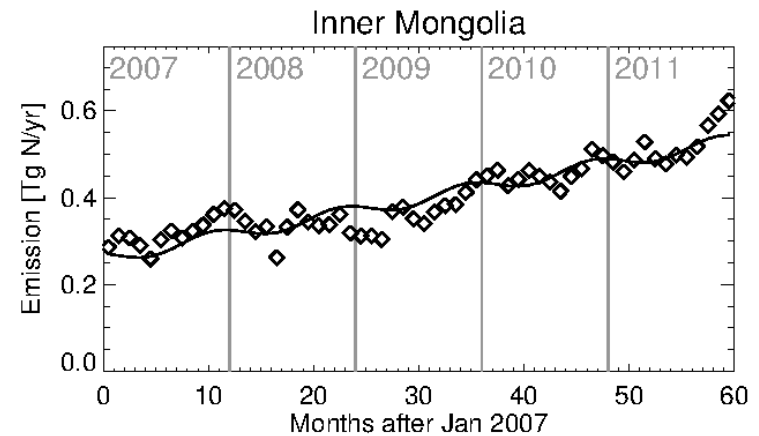
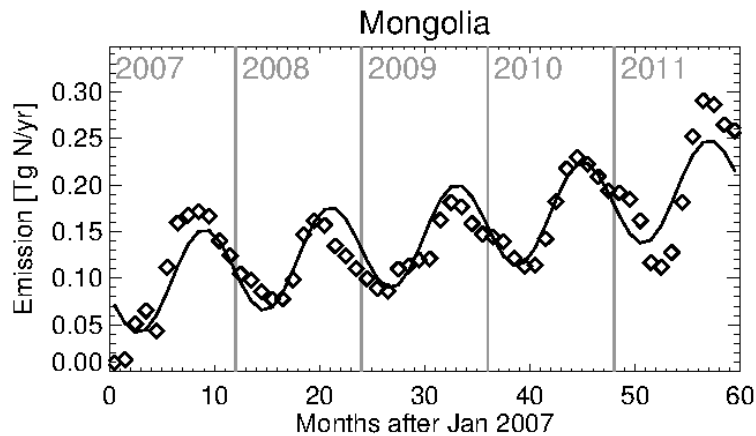
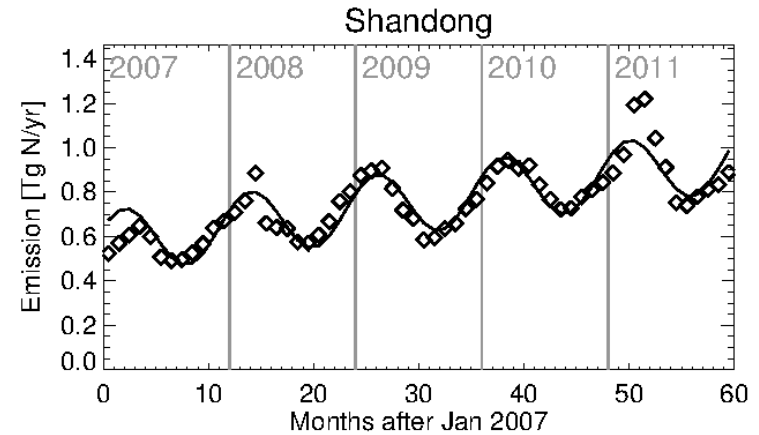
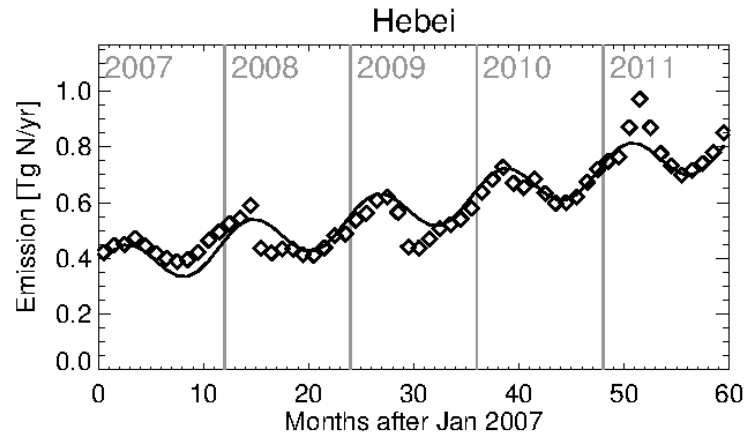
- New power plants in Inner Mongolia
- Distinct emissions along great rivers
- No emissions in North Korea
- Ship tracks

Agreement between observation and forecast

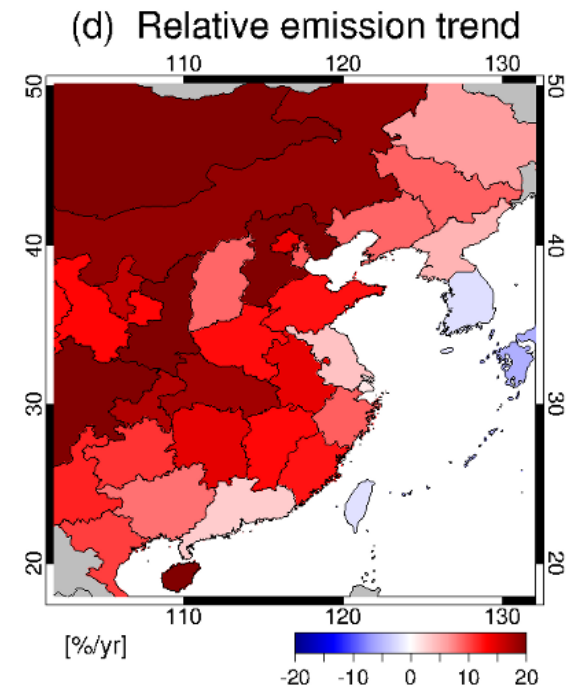
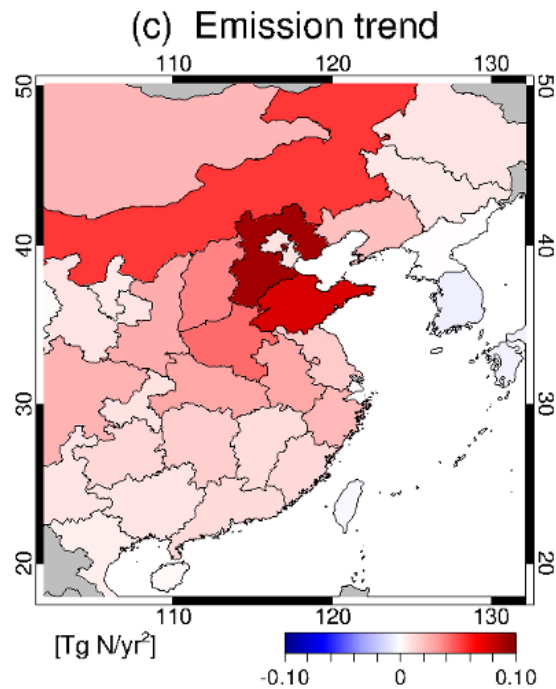
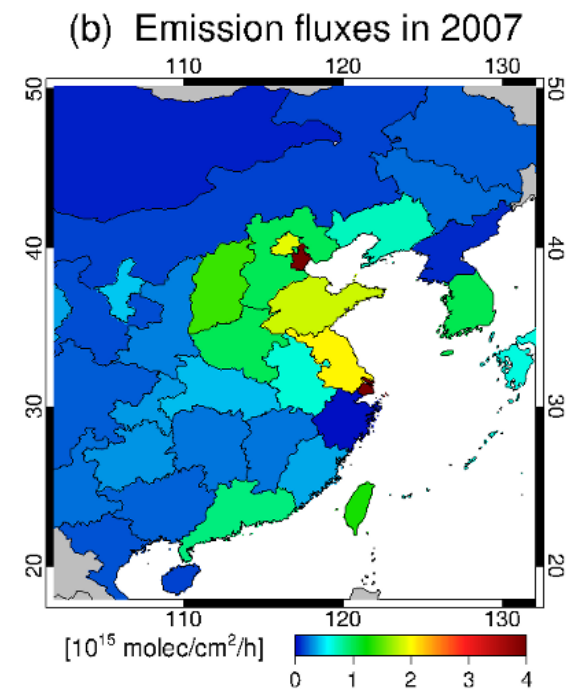
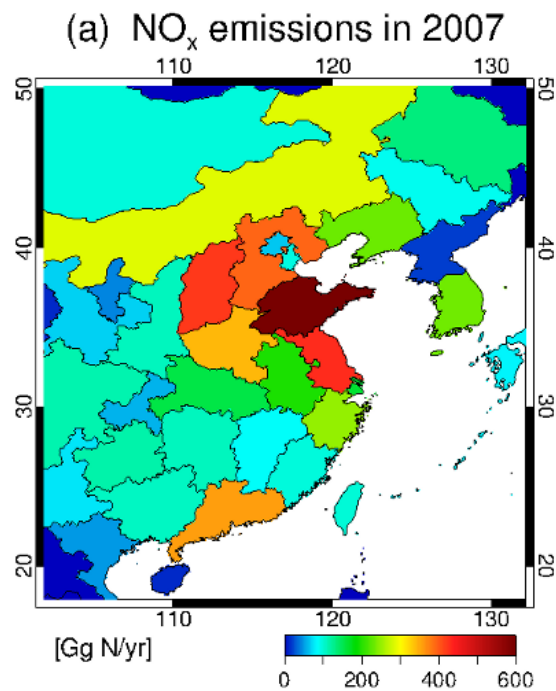


Emission estimates
from OMI data
May-December 2008

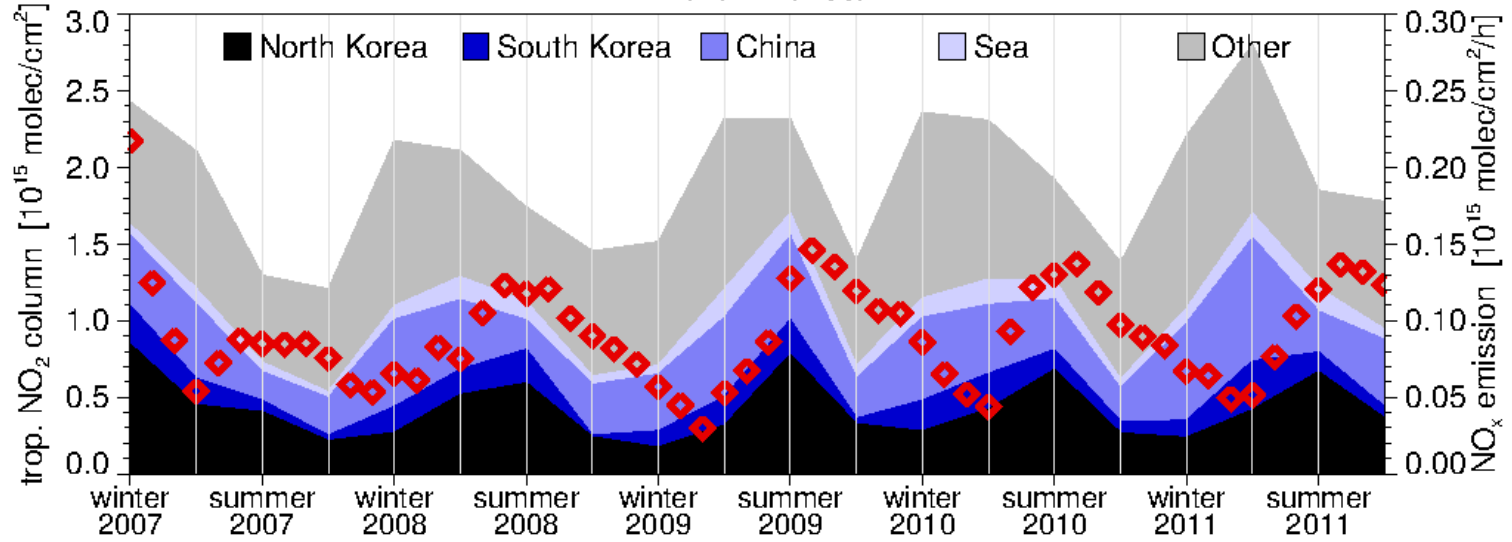
NO_x time series 2007-2011



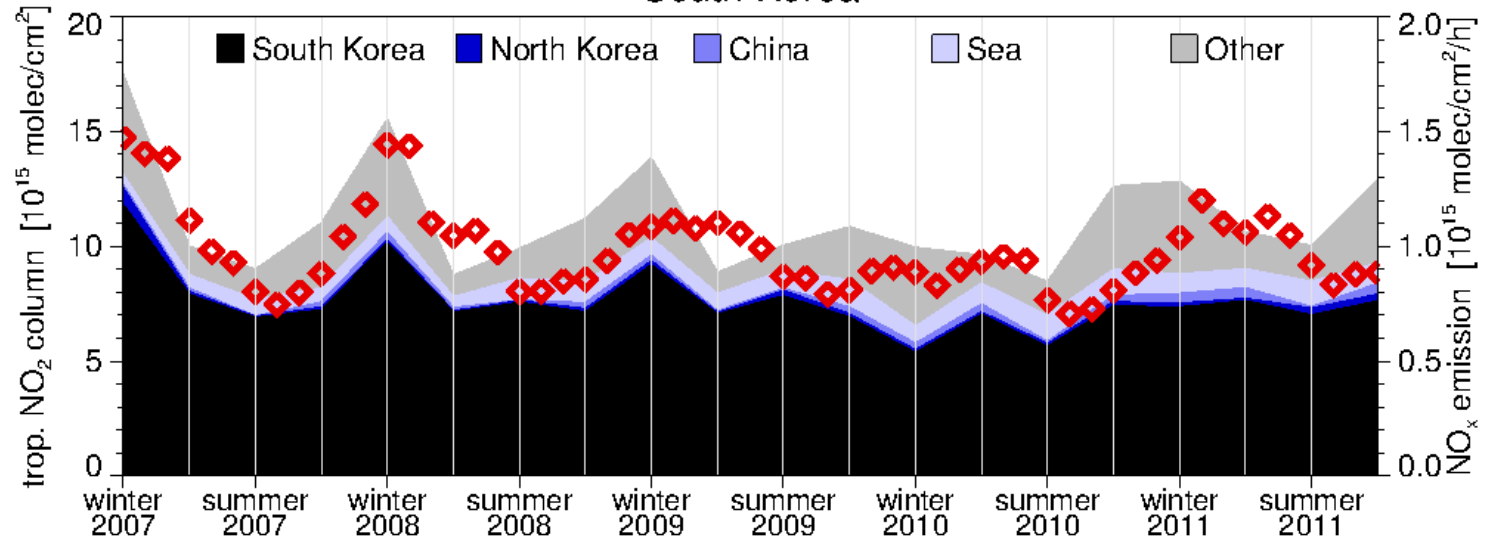
Emission trends by province



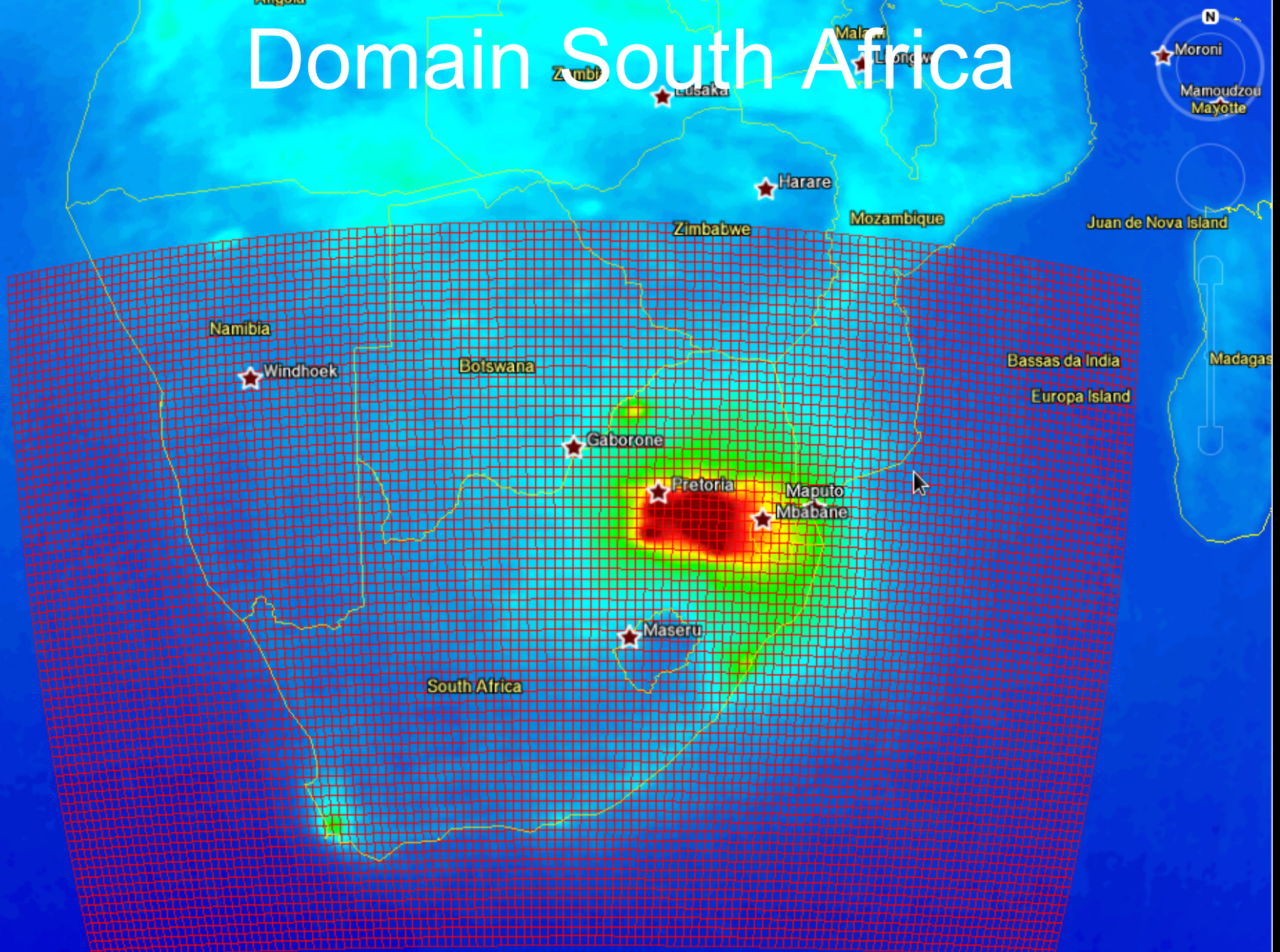
North Korea



South Korea



Domain South Africa



19°S–37°S, 10°E–42°E, 0.25° resolution, 9417 grid cells

South Africa:

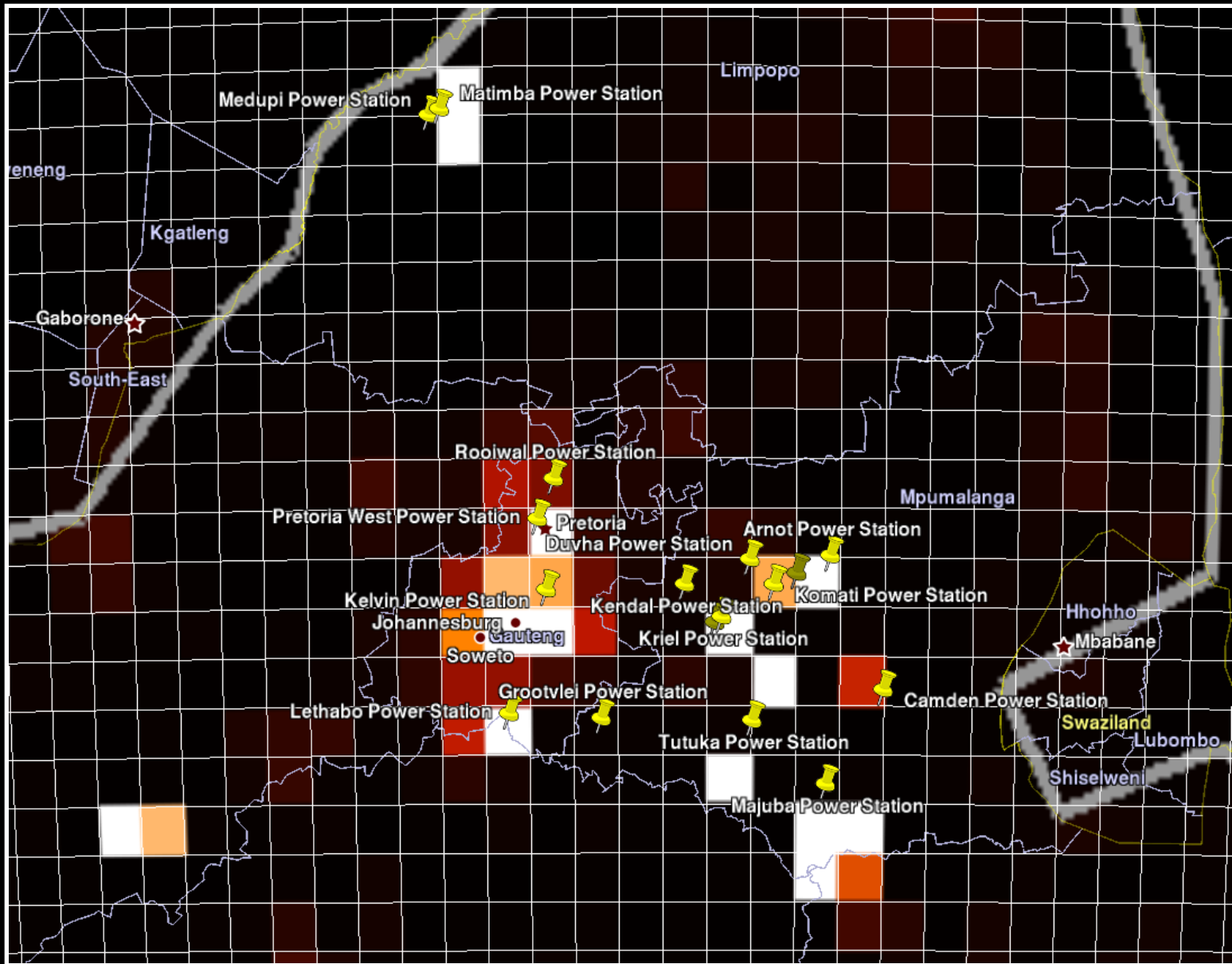
Emissions characterized by few hot spots (power plants, heavy industry)

Apriori emissions taken from **EDGAR v4.2**

- Total emissions too low
- Location and strength of hot spots generally wrong

EDGAR v4.2

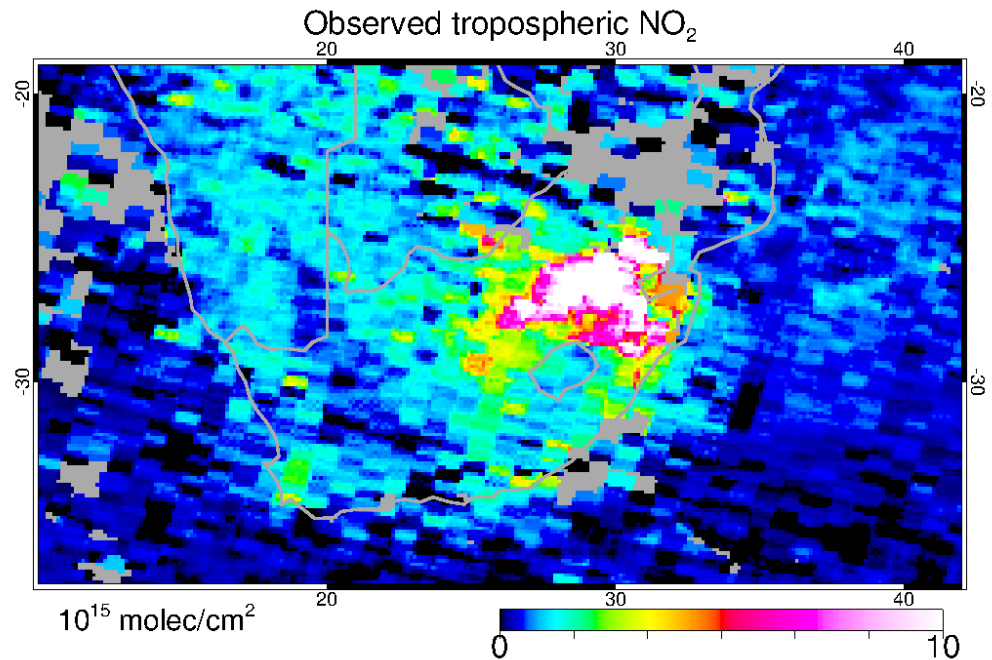
low  high



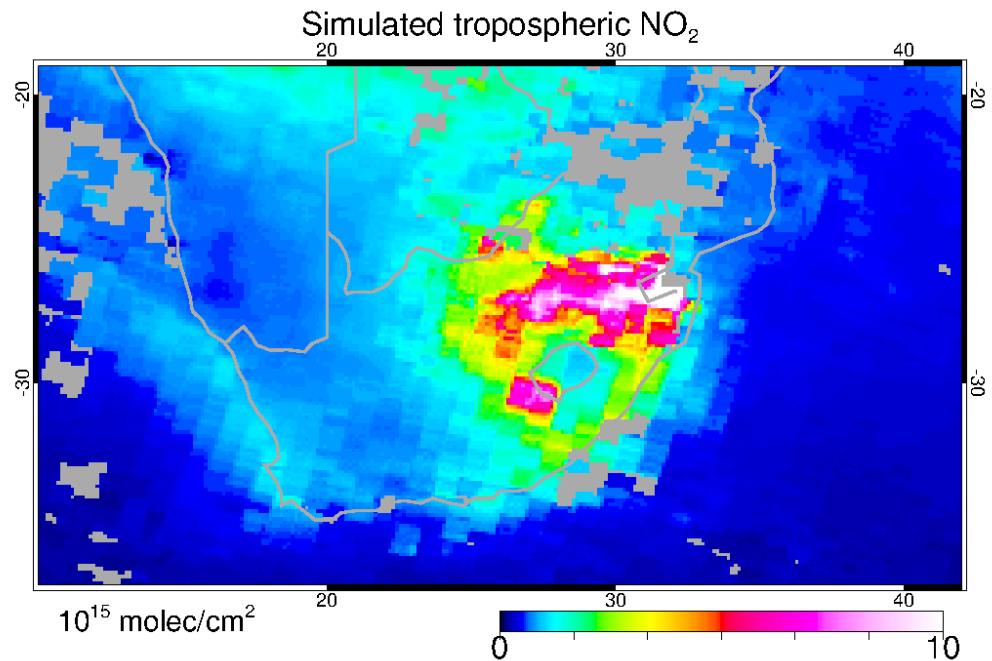
200 km

First results

GOME-2 observations
January 2008

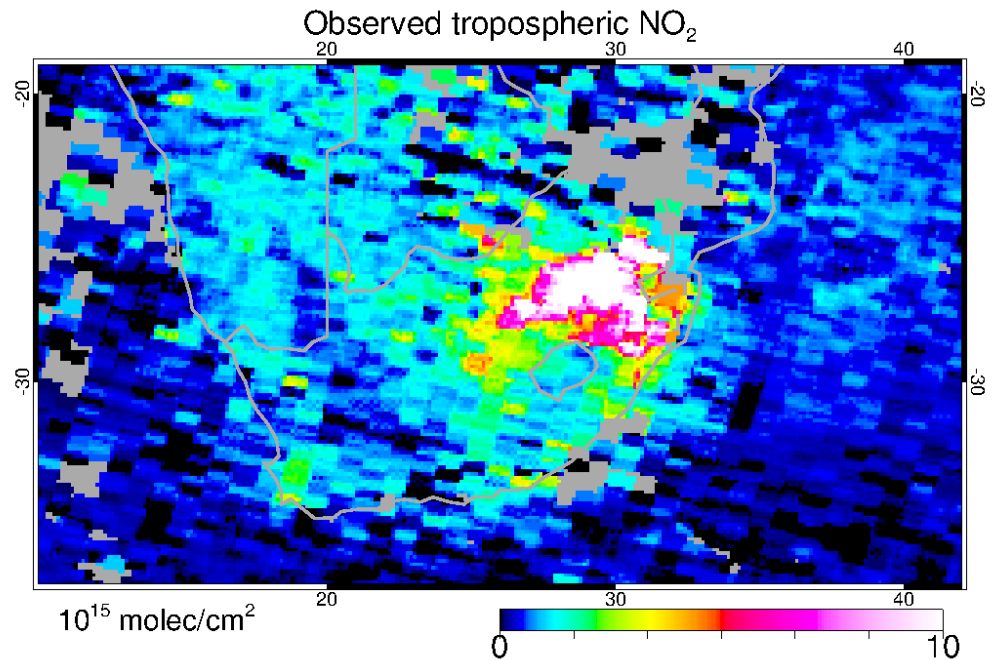


Colocated simulations
Based on EDGAR v4.2
No assimilation

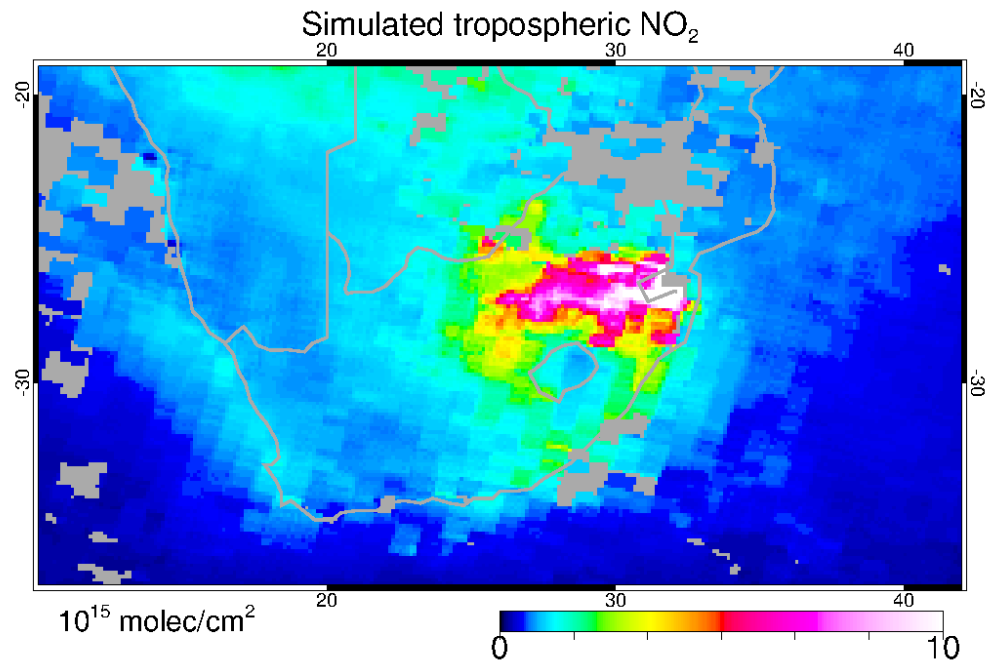


First results

GOME-2 observations
January 2008

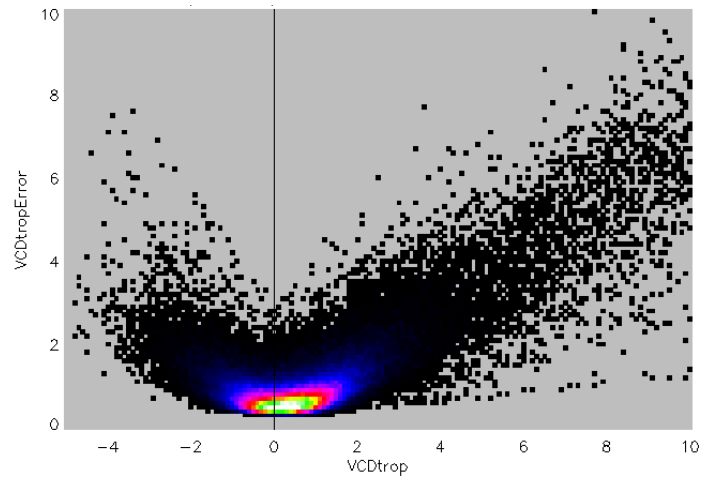


Colocated simulations
Assimilated observations

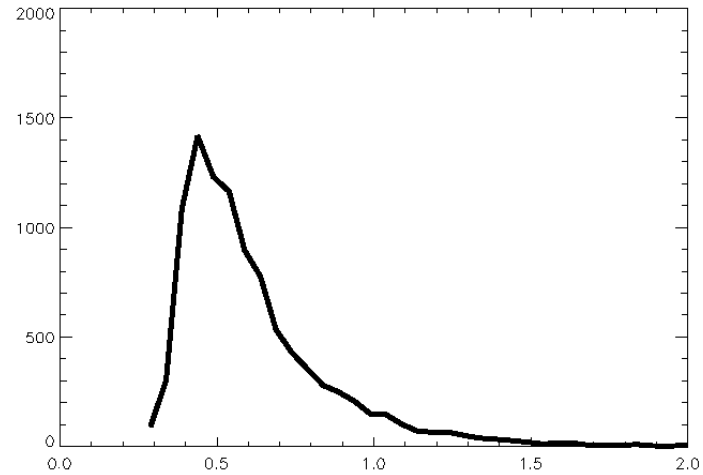


Observation error (tropospheric NO₂)

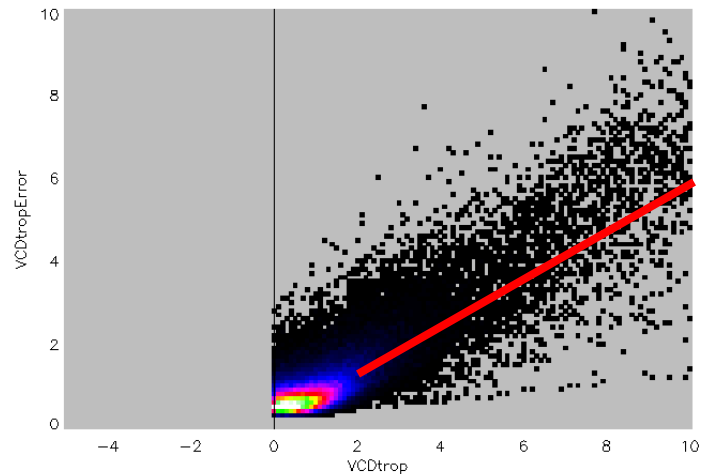
Retrieved column and error



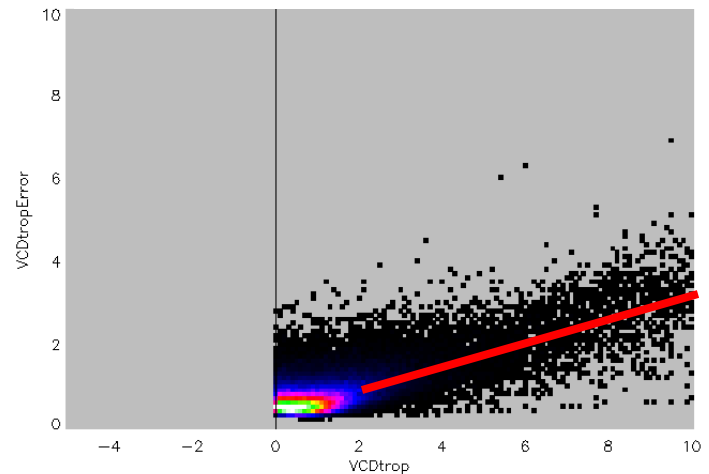
Error distribution around 0



Negative values put to zero



Reduction of relative error



New results

GOME-2 observations
2010

Concentration simulation

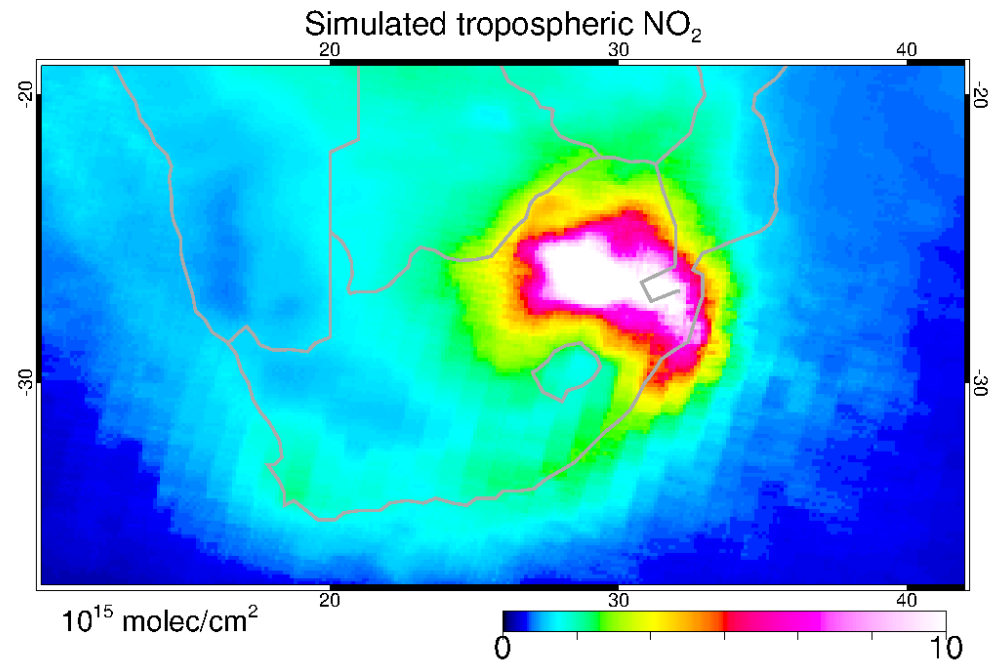
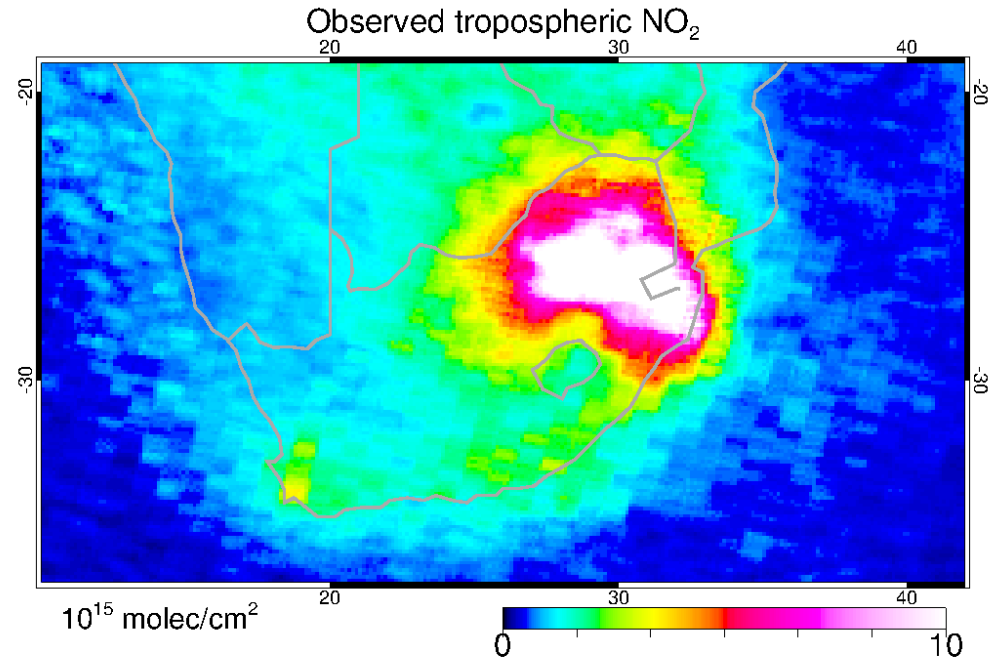
Emission injection height
according to sector

Source-receptor (sensitivity) calculation

Backward trajectory
calculation

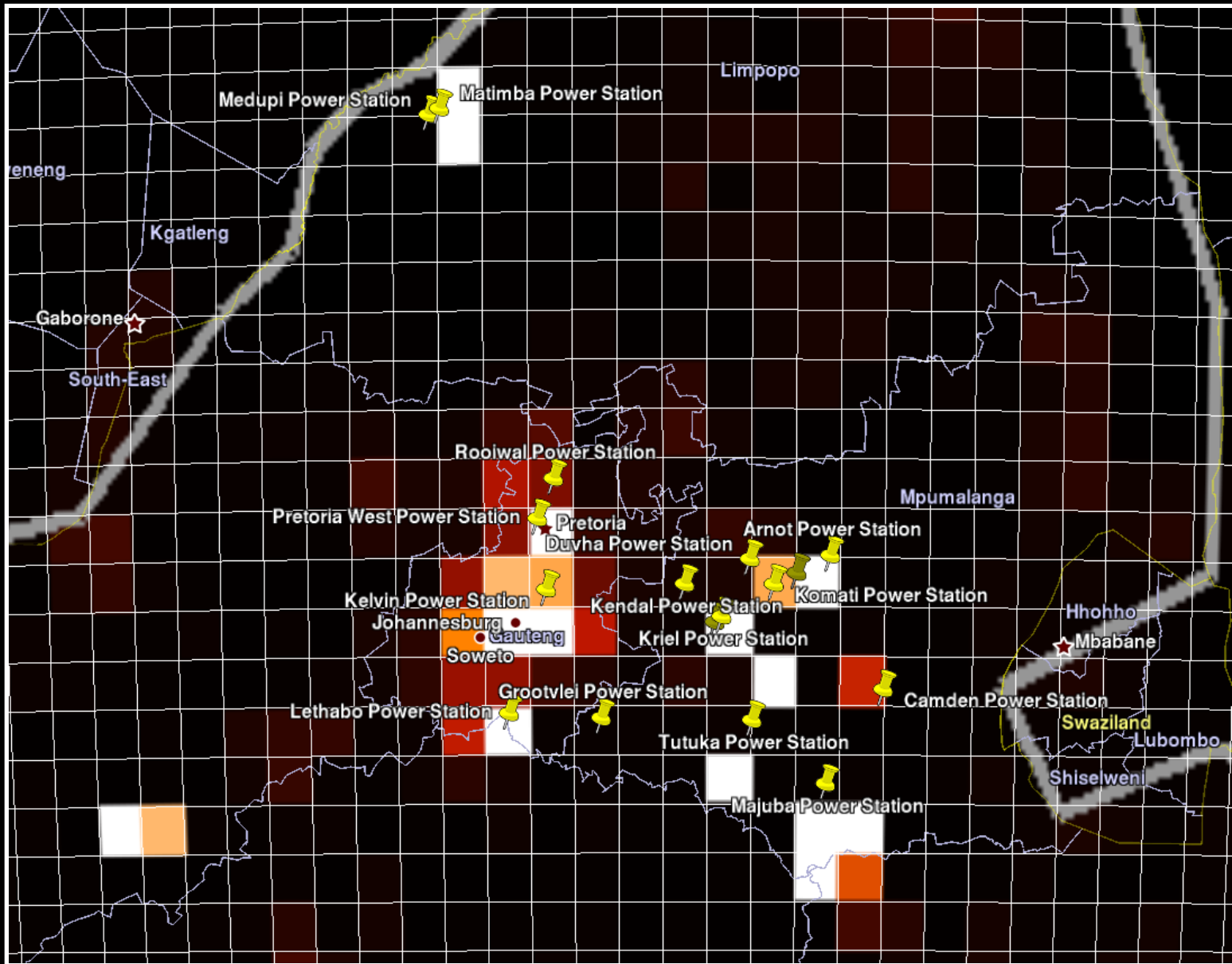
Emission update

- Update NO_x -correlated pollutants
- Noise and bias reduction over remote areas



EDGAR v4.2

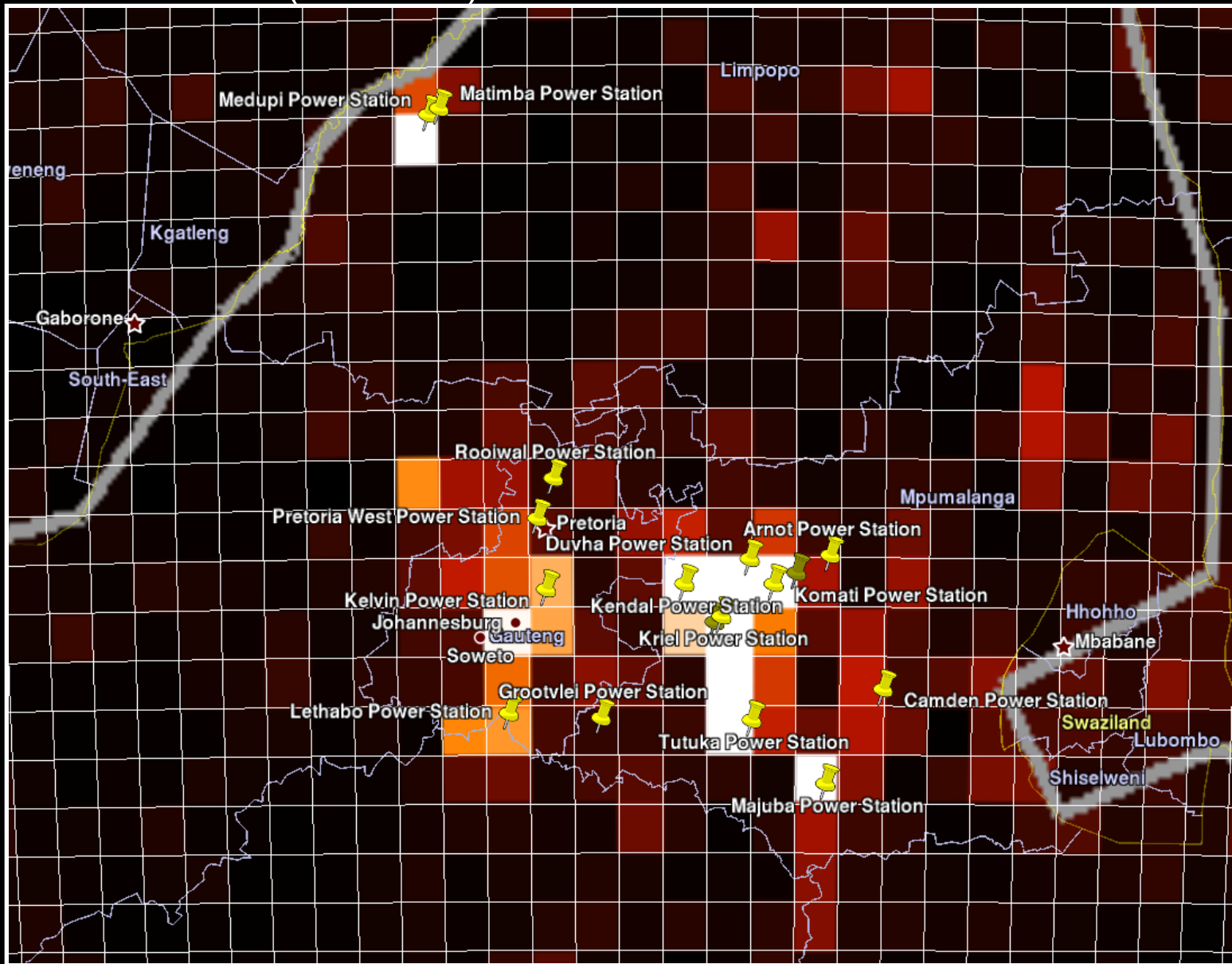
low  high



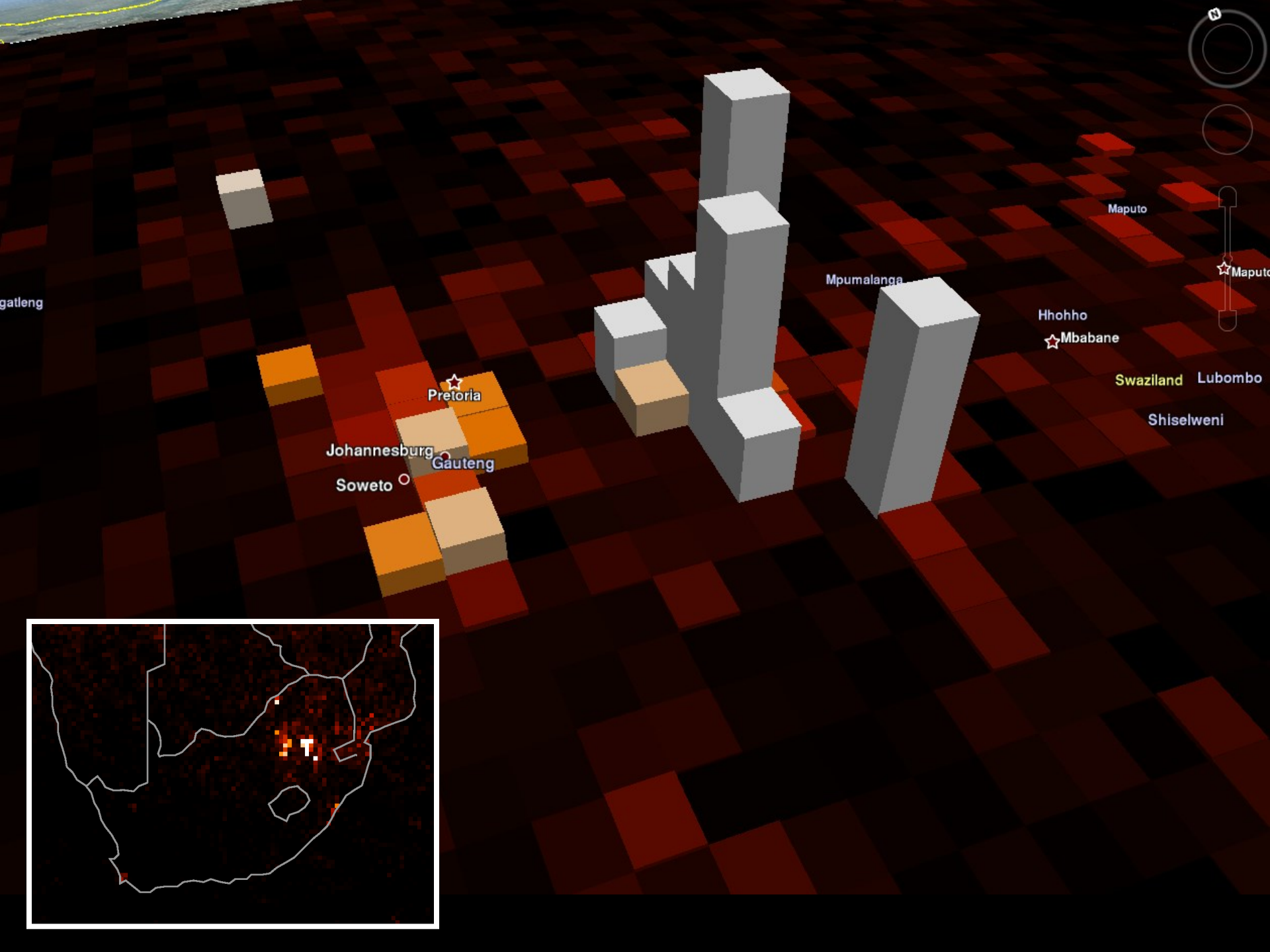
200 km

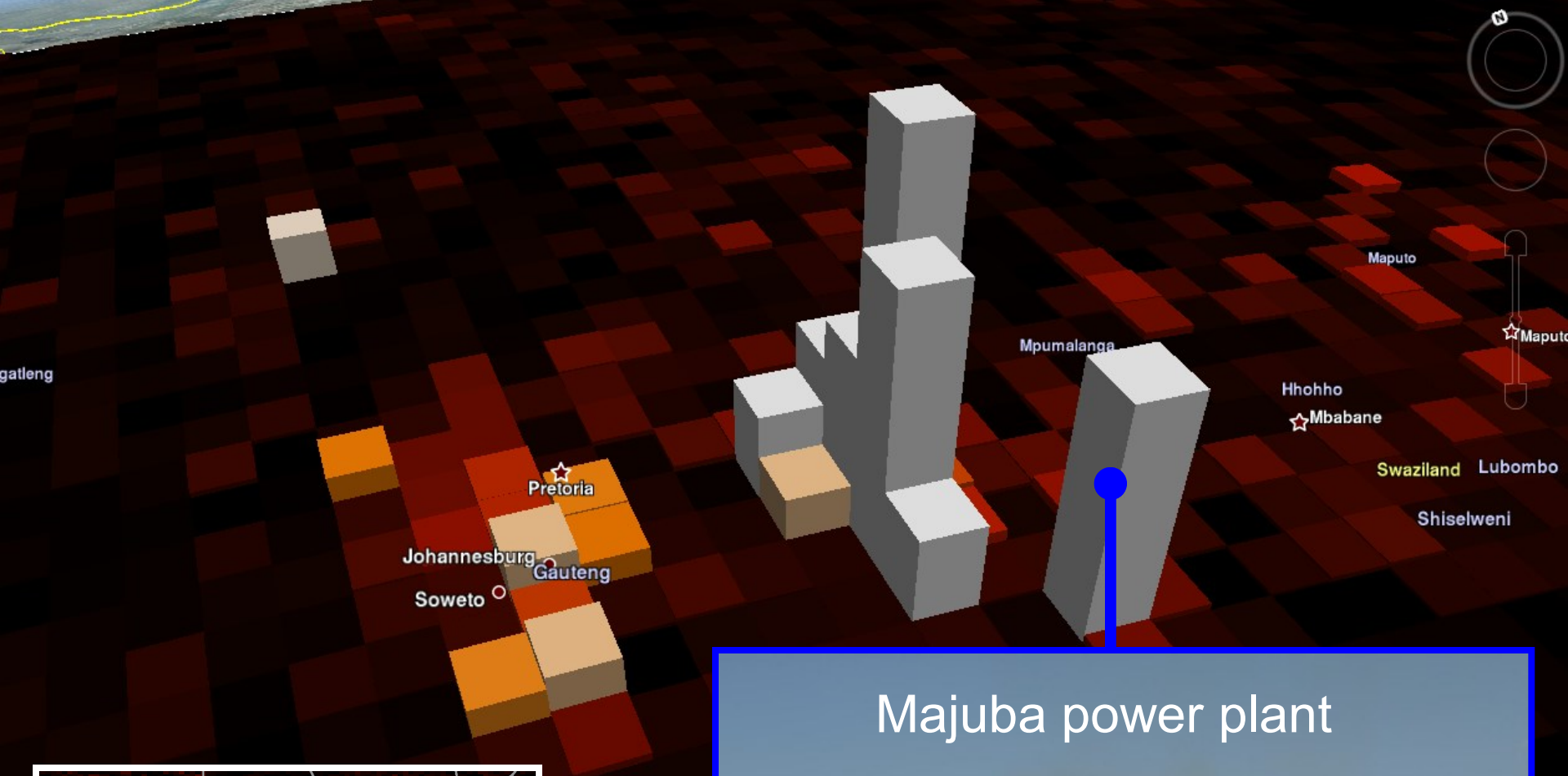
DECSO (with OMI)

low  high

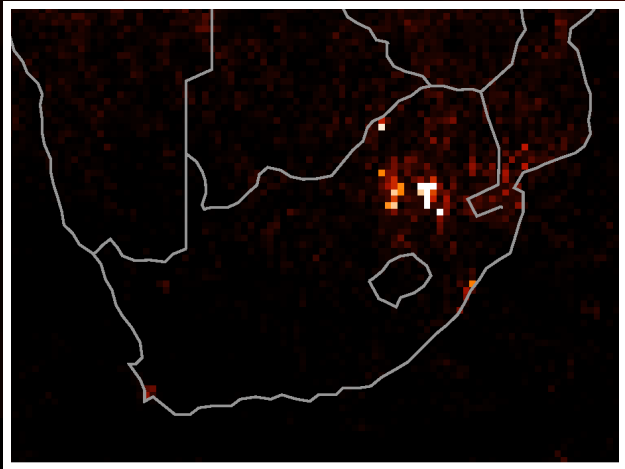


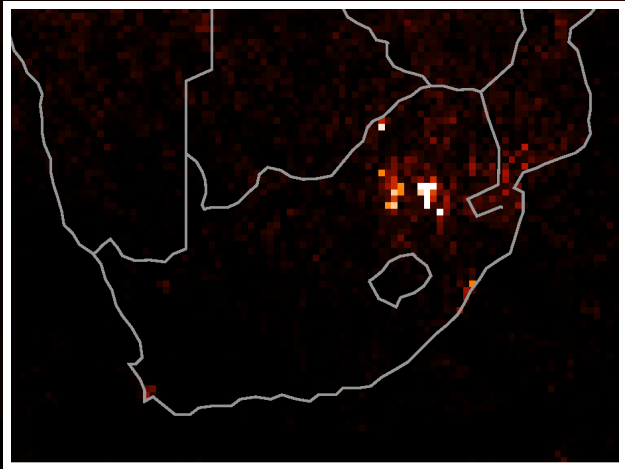
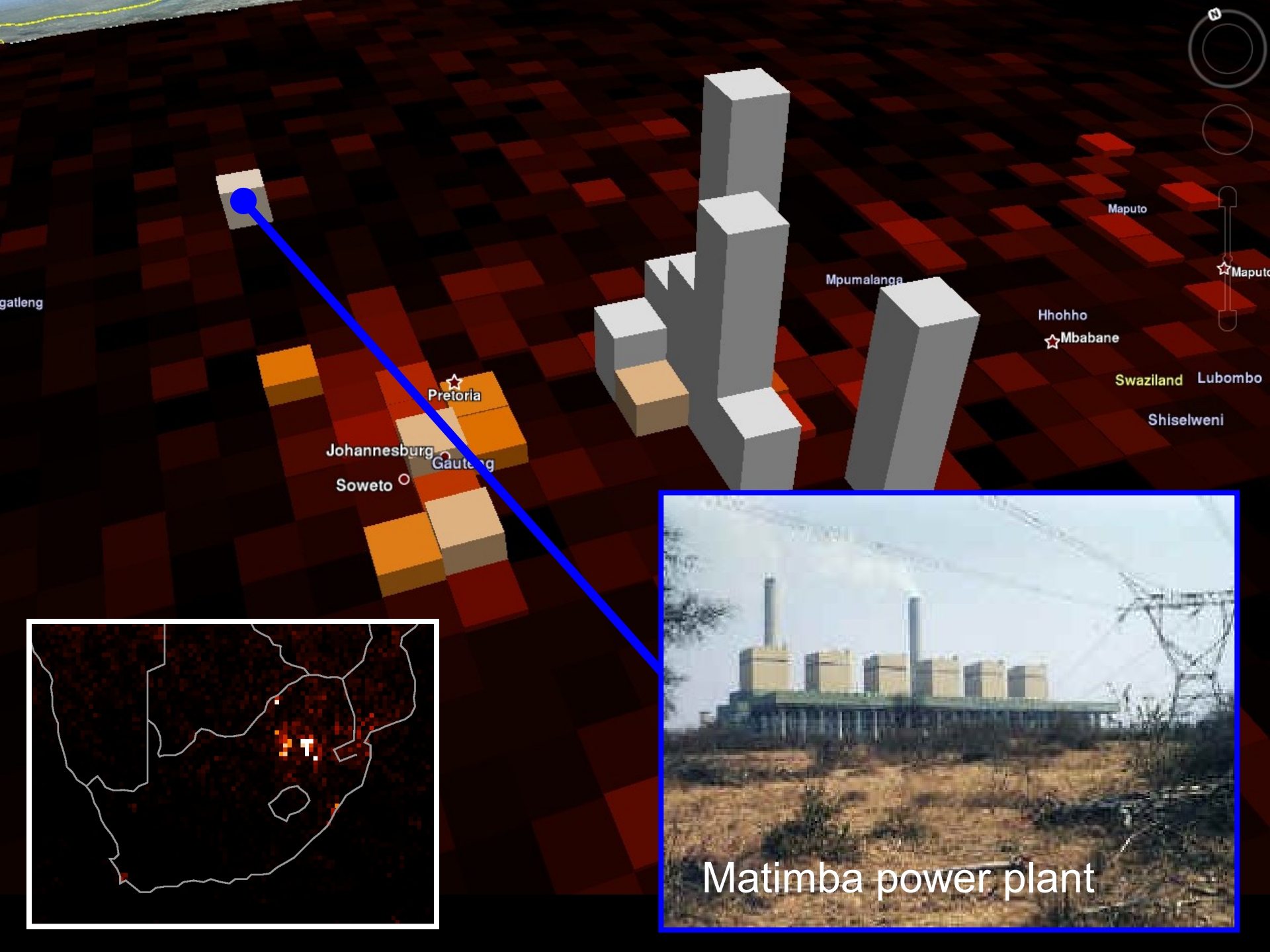
200 km

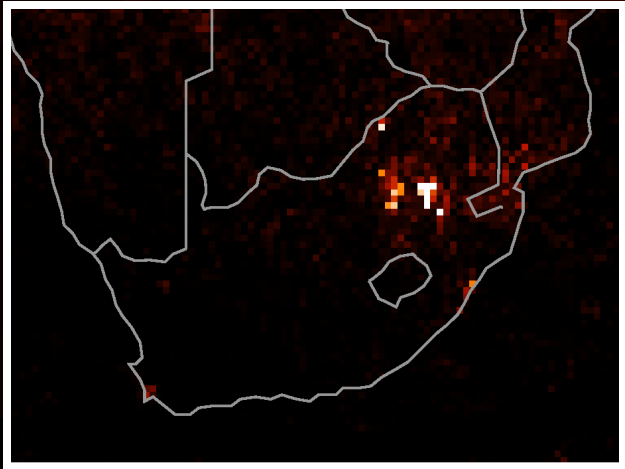


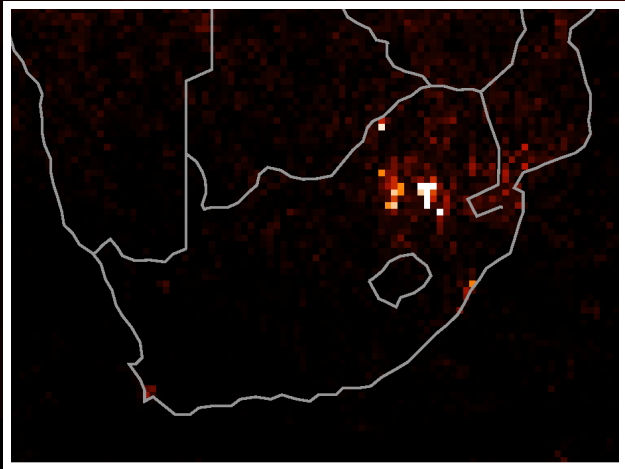
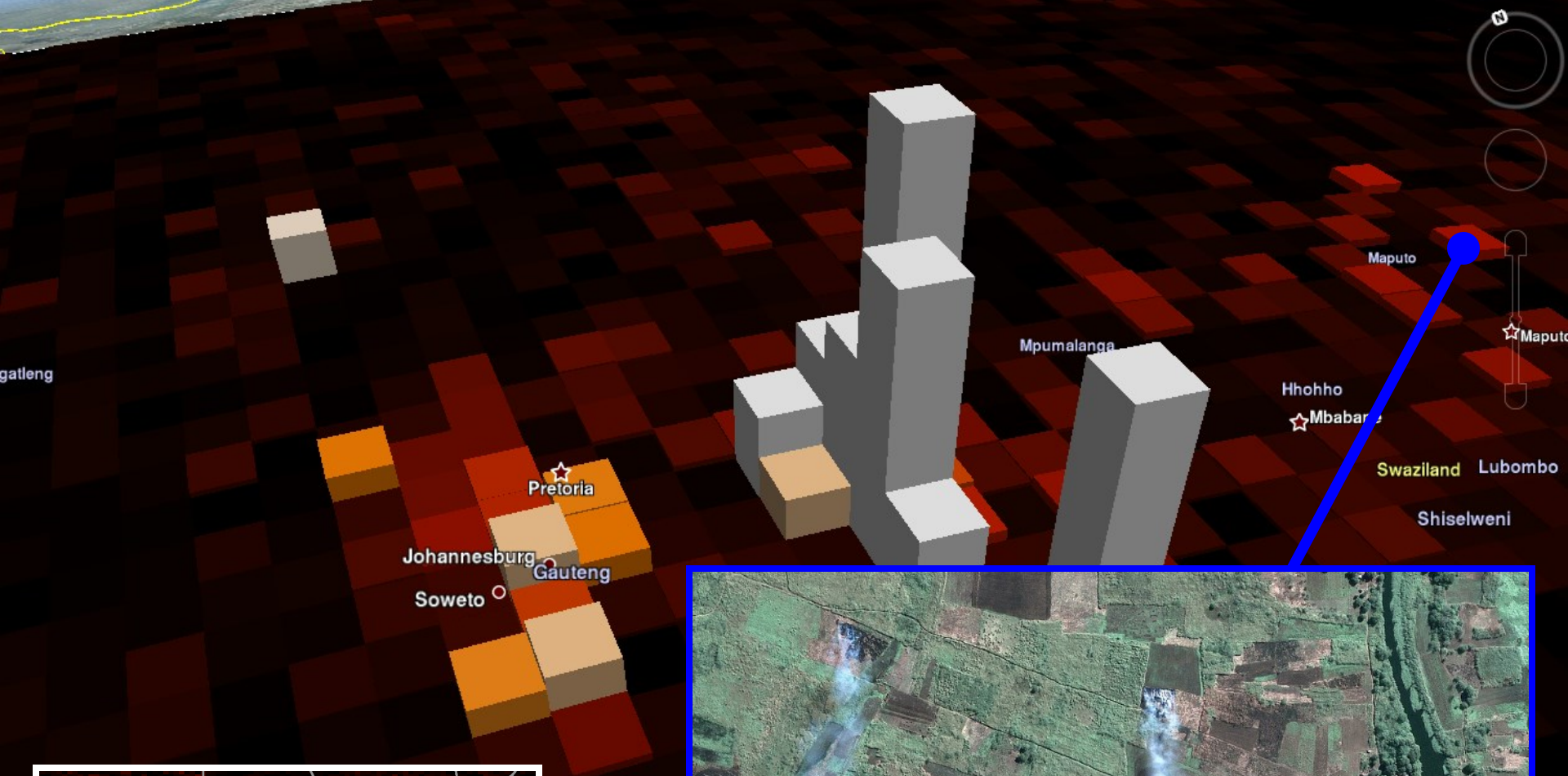


Majuba power plant









Algorithm summary

- The presented method is a promising new technique for top-down emission estimates from satellite observations.
- The algorithm is fast ($<1\text{h}$), enabling daily assimilation of satellite data.
- The algorithm only needs a forward CTM run; CTM is treated as a black box.

Results and Outlook (1)

- Successfully applied to China and South Africa.
- Better and up-to-date estimates of location and strength of NO_x emission sources.
- More validation necessary, e.g. with power plant emission data.
- Application to other regions (India, Middle East).
- Application to other species (e.g. SO₂).

Outlook (2)

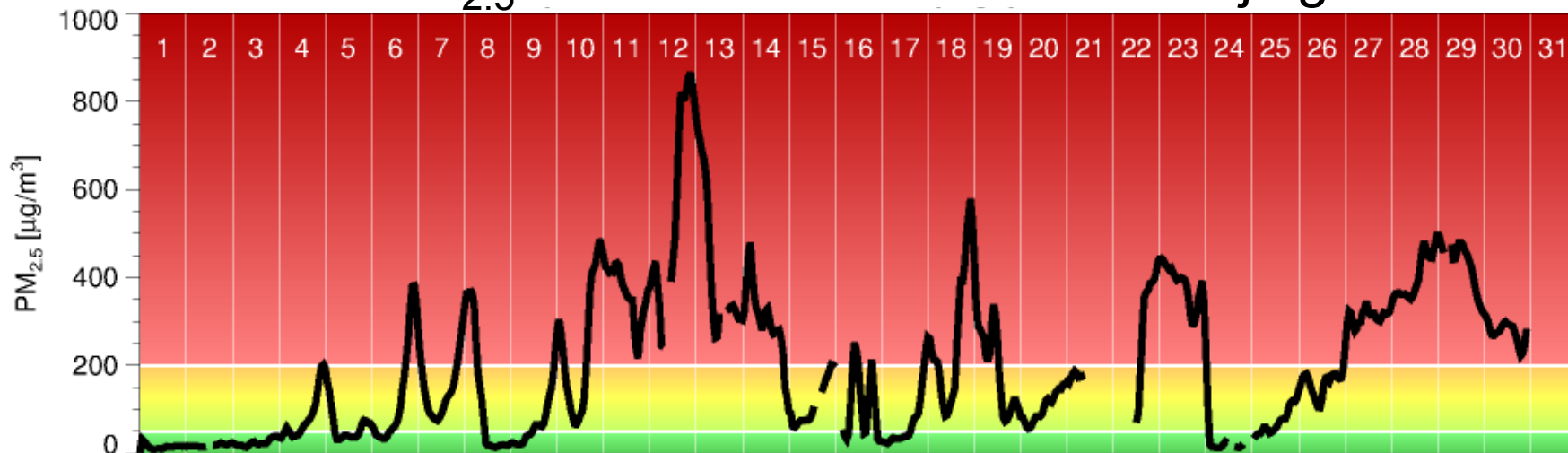
- Improve error estimation.
(Kalman formalism, autocorrelation of timeseries)
- Influence of satellite resolution on emission resolution.
(Smaller footprint of TROPOMI will improve results)
- Ingression of combined data sets.
(e.g. GOME-2 **and** OMI)

Air pollution in Beijing

January 2013

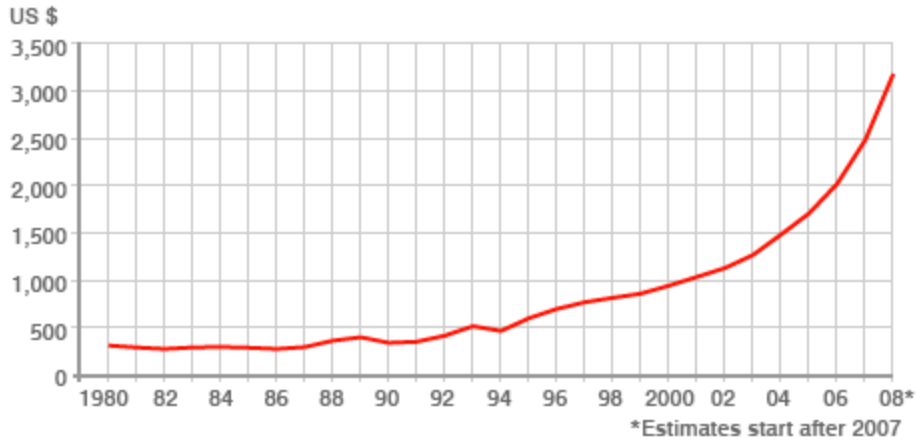


PM_{2.5} surface concentration in Beijing



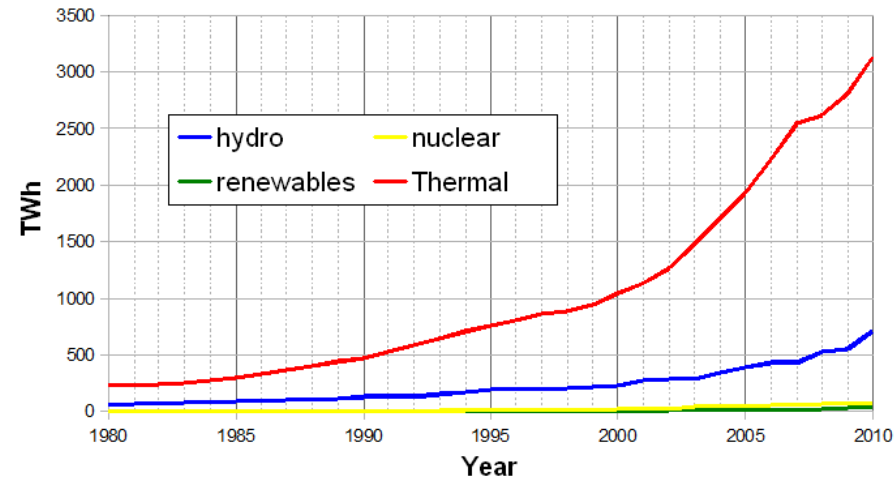
China: Economic indicators

Average annual income per capita, 1980-2008

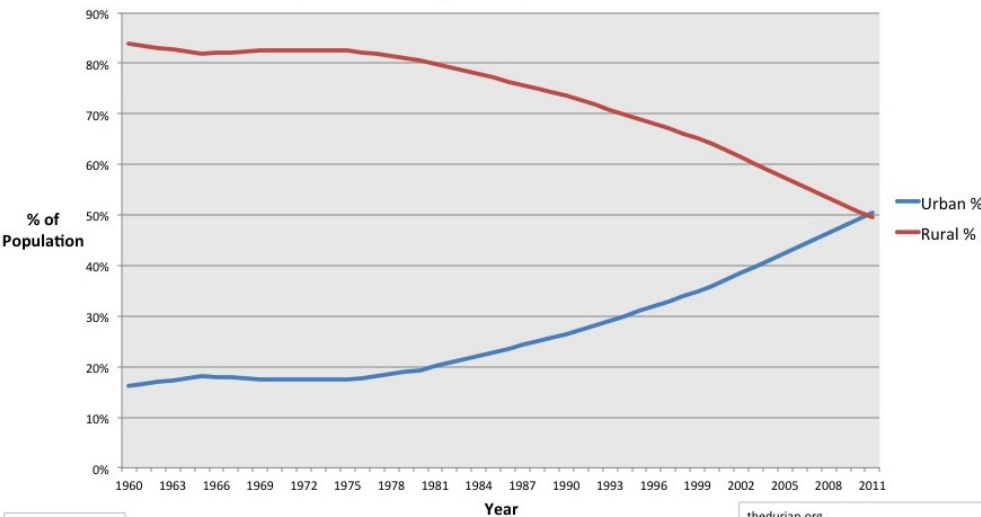


SOURCE: International Monetary Fund, World Economic Outlook Database, October 2008

China's electricity production, 1980-2010



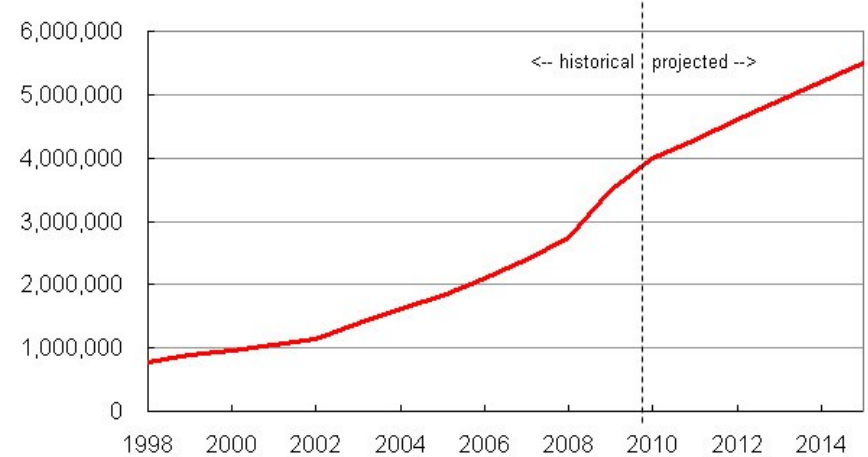
China's urbanization, 1980-2011



Source: World Bank

thedurian.org
huffingtonpost.com/john-wagner-givens

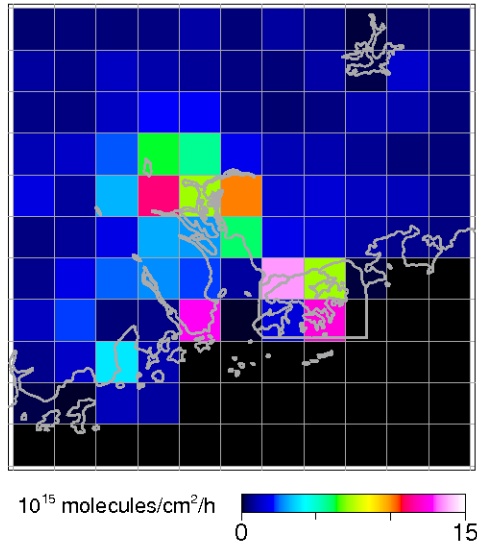
Number of vehicles in Beijing, 1998-2015



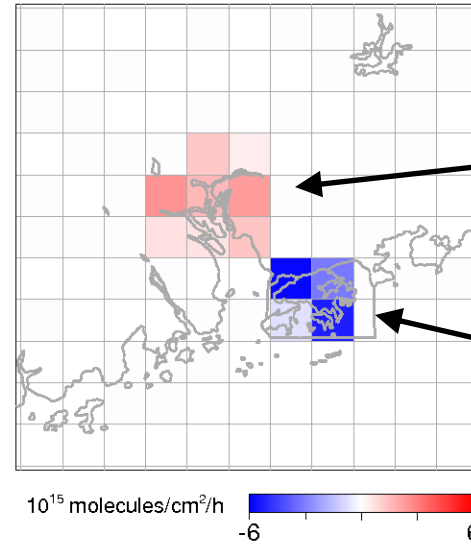
Source: China Statistical Yearbook, China Daily (17/2/09)

Closed loop test: Pearl River Delta region

(a) True



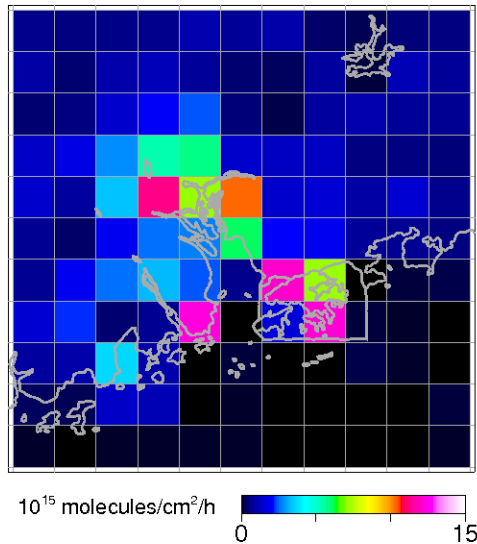
(b) True - Initial



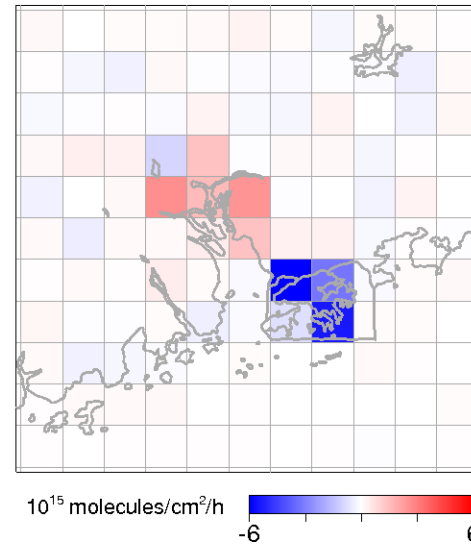
30% increase
Guangzhou

30% decrease
Hong Kong

(c) Mean assimilated



(d) Mean assimilated - Initial



Comparison of yearly NO_x emission totals for East China in Tg N/yr

	2006	2007	2008	2009	2010	2011
DECSO	–	5.63	5.91	6.06	7.09	7.96
EDGAR v4.2	5.03	5.34	5.93	–	–	–
INTEX-B	6.09	–	–	–	–	–
MEIC	–	–	7.54	–	8.28	–
REAS v1.1	4.44	4.55	4.65	4.76	4.86	–

Beijing province

